

Laplace approximation

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Outline

- Laplace approximation
- Bayesian logistic regression

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Laplace approximation

- Objective: construct a *Gaussian* distribution to approximate the posterior distribution
- Method: **second order Taylor expansion** at the posterior **mode** (i.e., MAP estimation)

Laplace approximation

- Given a joint probability $p(\boldsymbol{\theta}, \mathcal{D})$
- How to compute (approximate) $p(\boldsymbol{\theta}|\mathcal{D})$?

Let us do MAP estimation first

$$\boldsymbol{\theta}_0 = \underset{\boldsymbol{\theta}}{\operatorname{argmax}} \log p(\boldsymbol{\theta}, \mathcal{D}) = \underset{\boldsymbol{\theta}}{\operatorname{argmax}} \log p(\mathcal{D}|\boldsymbol{\theta})$$

Laplace approximation

- We then expand the log joint probability at the posterior mode

$$f(\boldsymbol{\theta}) \triangleq \log p(\boldsymbol{\theta}, \mathcal{D})$$

$$\begin{aligned} f(\boldsymbol{\theta}) &\approx f(\boldsymbol{\theta}_0) + \boxed{\nabla f(\boldsymbol{\theta}_0)}^\top (\boldsymbol{\theta} - \boldsymbol{\theta}_0) & \nabla f(\boldsymbol{\theta}_0) &= \mathbf{0} \\ &+ \frac{1}{2} (\boldsymbol{\theta} - \boldsymbol{\theta}_0)^\top \boxed{\nabla \nabla f(\boldsymbol{\theta}_0)} (\boldsymbol{\theta} - \boldsymbol{\theta}_0) & \nabla \nabla f(\boldsymbol{\theta}_0) &\prec 0 \quad \text{Why?} \end{aligned}$$

$$= f(\boldsymbol{\theta}_0) - \frac{1}{2} (\boldsymbol{\theta} - \boldsymbol{\theta}_0)^\top \mathbf{A} (\boldsymbol{\theta} - \boldsymbol{\theta}_0)$$

$$\mathbf{A} = -\nabla \nabla f(\boldsymbol{\theta}_0) \succ 0$$

Laplace approximation

$$f(\boldsymbol{\theta}) \triangleq \log p(\boldsymbol{\theta}, \mathcal{D})$$
$$\approx f(\boldsymbol{\theta}_0) - \frac{1}{2}(\boldsymbol{\theta} - \boldsymbol{\theta}_0)^\top \mathbf{A}(\boldsymbol{\theta} - \boldsymbol{\theta}_0)$$

$$p(\boldsymbol{\theta}, \mathcal{D}) \approx p(\boldsymbol{\theta}_0, \mathcal{D}) \exp\left(-\frac{1}{2}(\boldsymbol{\theta} - \boldsymbol{\theta}_0)^\top \mathbf{A}(\boldsymbol{\theta} - \boldsymbol{\theta}_0)\right)$$



Gaussian!

$$p(\boldsymbol{\theta}|\mathcal{D}) \approx \mathcal{N}(\boldsymbol{\theta}|\boldsymbol{\theta}_0, \mathbf{A}^{-1})$$

$$\boldsymbol{\theta}_0 = \underset{\boldsymbol{\theta}}{\operatorname{argmax}} \log p(\boldsymbol{\theta}, \mathcal{D})$$

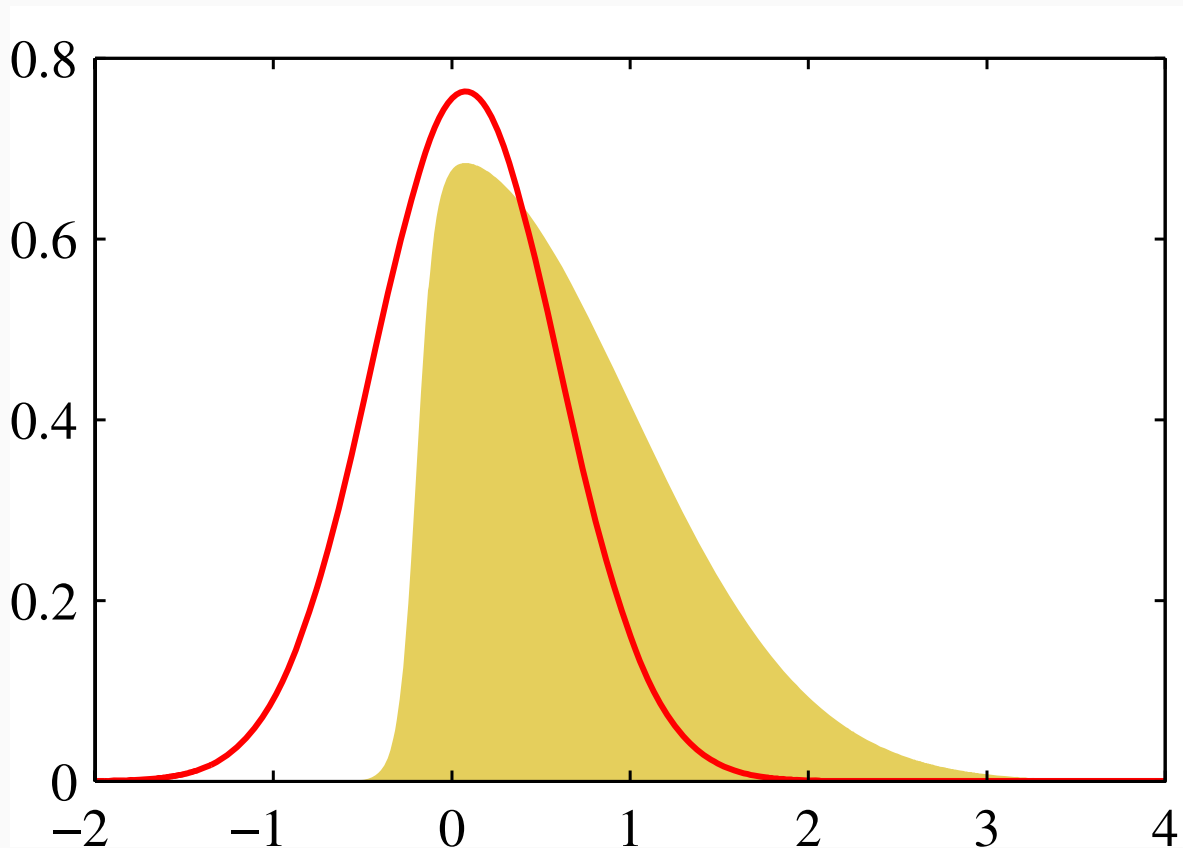
$$\mathbf{A} = -\nabla\nabla \log p(\boldsymbol{\theta}, \mathcal{D})|_{\boldsymbol{\theta}=\boldsymbol{\theta}_0}$$

Laplace approximation

$$p(z) \propto \exp(-z^2/2)\sigma(20z + 4)$$

Yellow: true

Red: Laplace approx.



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Bayesian Logistic regression

- Given a dataset $\{\phi_n, t_n\}$, where $t_n \in \{0, 1\}$, $\phi_n = \phi(\mathbf{x}_n)$ and $n = 1, \dots, N$, the likelihood function is given by

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{m}_0, \mathbf{S}_0)$$

$$p(\mathbf{t} | \mathbf{w}) = \prod_{n=1}^N y_n^{t_n} \{1 - y_n\}^{1-t_n}$$

$$\mathbf{t} = (t_1, \dots, t_N)^T$$

$$y_n = p(\mathcal{C}_1 | \phi_n) = \sigma(\mathbf{w}^T \phi_n)$$



$$p(\mathbf{w} | \mathbf{t}) \propto p(\mathbf{w})p(\mathbf{t} | \mathbf{w})$$

Bayesian logistic regression

$$\log p(\mathbf{w}, \mathbf{t}) = -\frac{1}{2}(\mathbf{w} - \mathbf{m}_0)^T \mathbf{S}_0^{-1}(\mathbf{w} - \mathbf{m}_0) + \sum_{n=1}^N \{t_n \ln y_n + (1 - t_n) \ln(1 - y_n)\} + \text{const}$$



$$\frac{d\sigma}{da} = \sigma(1 - \sigma).$$

$$\mathbf{S}_N = -\nabla \nabla \ln p(\mathbf{w} | \mathbf{t}) = \mathbf{S}_0^{-1} + \sum_{n=1}^N y_n(1 - y_n) \phi_n \phi_n^T$$




$$q(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{w}_{\text{MAP}}, \mathbf{S}_N^{-1})$$


Bayesian logistic regression

- Predictive distribution: given a new input ϕ

$$a = \phi^\top \mathbf{w}$$

$$q(\mathbf{w}) = \mathcal{N}(\mathbf{w} | \mathbf{w}_{\text{MAP}}, \mathbf{S}_N^{-1})$$


$$p(a | \mathbf{t}) \approx q(a) = \mathcal{N}(a | \mathbf{w}_{\text{MAP}}^\top \phi, \phi^\top \mathbf{S}_N^{-1} \phi) \quad \text{Predictive dist. of score}$$


$$p(\mathcal{C}_1 | \mathbf{t}) = \int \sigma(a) q(a) da \quad \text{Numerical quadrature}$$

What you need to know

- The general idea of Laplace's Approximation
- Being able to implement it