

# Online Bayesian Sparse learning with Spike-and-Slab Priors

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# Outline

- 1. Motivation
- 2. Spike and Slab prior
- 3. Online inference
- 4. Experiments on real-world data
- 5. Summary



#### 1. Motivation:

• Many predictive tasks involve a large number of features, e.g., Click-Through (CTR) prediction.

- Too many features could
  - I. lead to <u>complicate</u> models, thus request massive training data and computational resources (to avoid over-fitting)
  - II. be memory or computationally <u>intensive</u>, not handy for online prediction
- Advantages of Sparse learning
  - I. Computational efficiency
  - II. Good interpretations and benefit feature engineering



- 2. Spike and Slab prior
  - How non-Bayesian people get sparsity?
  - •L1 regularize

•

$$\hat{\beta} \equiv \underset{\beta}{\operatorname{argmin}} \left( \|y - X\beta\|^2 + \lambda \|\beta\|_1 \right)$$
  
.1 & L2 mixture regularize(Elastic Net)  
$$\hat{\beta} \equiv \underset{\beta}{\operatorname{argmin}} \left( \|y - X\beta\|^2 + \lambda_2 \|\beta\|^2 + \lambda_1 \|\beta\|_1 \right)$$

•Sparse coding, Dictionary learning, Compressed sensing...

All shrinkage uniformly over all feature weights!



- 2. Spike and Slab prior How Bayesian people get sparsity?
  - •Spike and Slab priors :

Introduce binary selection indicators  $s_1, s_2, \ldots, s_d$  on each weight



 $\mathsf{Mild}\;\mathsf{Regularize}\;(\mathsf{slab})$ 



Strong shrinkage(**spike**)



# 2. Spike and Slab prior How Bayesian people get sparsity?

•Spike and Slab priors : Introduce binary selection indicators  $s_1, s_2, \ldots, s_d$  on each weight

$$p(\mathbf{y}, \mathbf{s}, \mathbf{w} | \rho_0, \tau_0, \mathbf{X}) = p(\mathbf{s} | \rho_0) p(\mathbf{w} | \mathbf{s}, \tau_0) p(\mathbf{y} | \mathbf{w}, \mathbf{X})$$
  

$$p(\mathbf{s} | \rho_0) = \prod_{j=1}^d \text{Bernoulli}(s_j | \rho_0) = \prod_{j=1}^d \rho_0^{s_j} (1 - \rho_0)^{(1 - s_j)}$$
  

$$p(\mathbf{w} | \mathbf{s}, \tau_0) = \prod_{j=1}^d p(w_j | s_j, \tau_0) = \prod_{j=1}^d \mathbf{s}_j \mathcal{N}(w_j | 0, \tau_0) + (1 - s_j) \overline{\delta(w_j)}$$
  
Selective shrinkage based on indicator  

$$p(\mathbf{y} | \mathbf{w}, \mathbf{X}) = \prod_{j=1}^n p(y_j | \mathbf{w}, \mathbf{x}_j)$$



The overview of the whole model

• Focus on general binary classification problems, with the form:

$$p(y_j | \mathbf{w}, \mathbf{x}_j) = \Phi(y_j \mathbf{w}^\top \mathbf{x}_j) \text{ where } \Phi(t) = \int_{-\infty}^t \mathcal{N}(u|0, 1) du$$
  
data likelihood!

- Assign spike and slab **prior** over model weights  $p(\mathbf{s} \mid \rho_0)p(\mathbf{w} \mid \mathbf{s}, \tau_0) = \prod_{j=1}^d \rho_0^{s_j} (1 \rho_0)^{(1 s_j)} \prod_{j=1}^d s_j \mathcal{N}(w_j \mid 0, \tau_0) + (1 s_j) \delta(w_j)$
- Goal of Bayesian inference: get the posterior  $p(\mathbf{y}, \mathbf{s}, \mathbf{w} \mid \rho_0, \tau_0, \mathbf{X}) = p(\mathbf{s} \mid \rho_0) p(\mathbf{w} \mid \mathbf{s}, \tau_0) p(\mathbf{y} \mid \mathbf{w}, \mathbf{X}) \quad \text{Joint distribution !}$   $p(\mathbf{w}, \mathbf{s} \mid \mathbf{X}, \mathbf{y}, \rho_0, \tau_0) = \frac{p(\mathbf{w}, \mathbf{s}, \mathbf{y} \mid \mathbf{X}, \rho_0, \tau_0)}{\int p(\mathbf{w}, \mathbf{s}, \mathbf{y} \mid \mathbf{X}, \rho_0, \tau_0) d\mathbf{w} d\mathbf{s}} \quad \text{Posterior !}$



The overview of the whole model

• Goal of Bayesian inference: get the posterior

$$p(\mathbf{w}, \mathbf{s} \mid \mathbf{X}, \mathbf{y}, 
ho_0, au_0) = rac{p(\mathbf{w}, \mathbf{s}, \mathbf{y} \mid \mathbf{X}, 
ho_0, au_0)}{\int p(\mathbf{w}, \mathbf{s}, \mathbf{y} \mid \mathbf{X}, 
ho_0, au_0) \mathrm{d}\mathbf{w} \mathrm{d}\mathbf{s}}$$

Normalizer, constant but intractable

- Exact calculation is not feasible
- MCMC sampling: slow converge with high dimensional space
- Expectation Propagation(EP):

approximate the intractable posterior with some easy distribution family!



- 3. Online Inference
- Expectation Propagation:
   Pick the exponential (Exp) family as approximation, which offers good
   closure property under multiplication

$$q(\boldsymbol{\theta}) = \exp\left(\boldsymbol{\lambda}^{\top} T(\boldsymbol{\theta}) - A(\boldsymbol{\lambda})\right)$$

• Factorize both the exact posterior & approximation posterior  $p(\theta) \propto f_0(\theta) \prod_j f_j(\theta) \stackrel{\text{likelihood}}{=} q(\theta) \propto \tilde{f}_0(\theta) \prod_j \tilde{f}_j(\theta)$ Global approximation by factor-wise approximation!  $\tilde{f}_0(\theta) \approx f_0(\theta), \tilde{f}_j(\theta) \approx f_j(\theta)$   $\tilde{f}_0(\theta), \tilde{f}_1(\theta) \dots, \tilde{f}_n(\theta) \in \text{Exp}(\theta)$ 



• Expectation Propagation, standard version

• Go through every factor  $f_0(\boldsymbol{\theta}), \{f_j\}_{j=1}^n$ 

 $q^{\setminus j}(\boldsymbol{\theta}) \propto rac{q(\boldsymbol{\theta})}{\tilde{f}_j(\boldsymbol{\theta})}$  Calibration distribution (context)  $q^*(\boldsymbol{\theta}) = \operatorname{argmin} \quad \operatorname{KL}\left(q^{\setminus j}(\boldsymbol{\theta})f_j(\boldsymbol{\theta})\|q(\boldsymbol{\theta})\right)$  $\tilde{f}_j^{\operatorname{new}}(\boldsymbol{\theta}) \propto rac{q^*(\boldsymbol{\theta})}{q^{\setminus j}(\boldsymbol{\theta})}$  Moment match!

•Must cyclically go-through all data points and approximate corresponding factors ... *inefficient storage when # of data is large!* 



- 3. Online Inference
- Stochastic Expectation Propagation
  - estimate an average approx. likelihood factor
  - Update the in average approx. likelihood factor an online fashion!

$$q(\boldsymbol{\theta}) \propto \tilde{f}_0(\boldsymbol{\theta}) \prod_j \tilde{f}_j(\boldsymbol{\theta})$$

Standard Expectation Propagation

$$p(\boldsymbol{\theta}) \propto f_0(\boldsymbol{\theta}) \prod_{j=1}^n f_j(\boldsymbol{\theta})$$

Exact posterior

$$q(\boldsymbol{\theta}) \propto \tilde{f}_0(\boldsymbol{\theta}) \left( \tilde{f}_a(\boldsymbol{\theta}) \right)^n$$

Stochastic Expectation Propagation



- 3. Online Inference
- Stochastic Expectation Propagation
  - Initialize  $\tilde{f}_0(\boldsymbol{\theta})$   $[\tilde{f}_a(\boldsymbol{\theta})$
  - Go through each data samples (j = 1, ..., n)

$$\begin{split} q^{\backslash j}(\boldsymbol{\theta}) &\propto \frac{q(\boldsymbol{\theta})}{\tilde{f}_{a}(\boldsymbol{\theta})} \\ q^{*}(\boldsymbol{\theta}) &= \operatorname{argmin} \quad \mathrm{KL}\big(q^{\backslash j}(\boldsymbol{\theta})f_{j}(\boldsymbol{\theta}) \| q(\boldsymbol{\theta})\big) \\ \tilde{f}_{j}^{\mathrm{new}}(\boldsymbol{\theta}) &\propto \frac{q^{*}(\boldsymbol{\theta})}{q^{\backslash j}(\boldsymbol{\theta})} \\ \tilde{f}_{a}^{\mathrm{new}}(\boldsymbol{\theta}) &= \frac{1}{n}\big((n-1)\tilde{f}_{a}(\boldsymbol{\theta}) + \tilde{f}_{j}^{\mathrm{new}}(\boldsymbol{\theta})\big) \quad \text{stochastic update} \\ &= (1-\epsilon)\tilde{f}_{a}(\boldsymbol{\theta}) + \epsilon \cdot \tilde{f}_{a}^{\mathrm{new}}(\boldsymbol{\theta}) \end{split}$$

learning rate



What we have as far?

- Spike and Slab Prior
- Stochastic Expectation Propagation framework

What the next step?

• Design the exact form of approximation factor: fully factorized form

$$p(\mathbf{y}, \mathbf{s}, \mathbf{w} | \rho_0, \tau_0, \mathbf{X}) = \prod_{i=1}^{d} \operatorname{Bernoulli}(s_i | \rho_0) \prod_{i=1}^{d} \underbrace{\left(s_i \mathcal{N}(w_i | 0, \tau_0) + (1 - s_i) \delta(w_i)\right)}_{i=1} \cdot \prod_{j=1}^{n} \underbrace{\Phi(y_j \mathbf{w}_{t_j}^\top \hat{\mathbf{x}}_j)}_{j=1}$$
  
Some Exp distribution family ? Some Exp distribution family



Design the exact form of approximation factor

 $p(\mathbf{y}, \mathbf{s}, \mathbf{w} | \rho_0, \tau_0, \mathbf{X}) = \prod_{i=1}^{d} \operatorname{Bernoulli}(s_i | \rho_0) \prod_{i=1}^{d} \underbrace{(s_i \mathcal{N}(w_i | 0, \tau_0) + (1 - s_i) \delta(w_i))}_{i=1} \cdot \prod_{j=1}^{n} \underbrace{\Phi(y_j \mathbf{w}_{t_j}^{\top} \hat{\mathbf{x}}_j)}_{i=1}$   $q(\mathbf{y}, \mathbf{s}, \mathbf{w}) \propto \prod_{i=1}^{d} \operatorname{Bernoulli}(s_i | \rho_0) \prod_{i=1}^{d} \underbrace{\operatorname{Bernoulli}(s_i | \rho_i) \mathcal{N}(w_i | \mu_{1i}, v_{1i})}_{i=1}}_{i=1} \operatorname{Bernoulli}(s_i | \rho_i) \mathcal{N}(w_i | \mu_{1i}, v_{1i})}_{i=1}$  maintain two types of average likelihood (two Gaussian!) approximations!

for positive samples & for negative samples correspondingly



By arranging the terms, we get the final form of approx. posterior

$$q(\mathbf{y}, \mathbf{s}, \mathbf{w})_{\text{Approx. factors on each weight prior}} \text{Approx. factor on each pos. sample} \\ \propto \prod_{i=1}^{d} \text{Bernoulli}(s_i|\rho_0) \text{Bernoulli}(s_i|\rho_i) \mathcal{N}(w_i|\mu_{1i}, v_{1i}) \mathcal{N}(w_i|\mu_{2i}^+, v_{2i}^+)^{n_i^+} \mathcal{N}(w_i|\mu_{2i}^-, v_{2i}^-)^{n_i^-} \\ \text{Approx. factor on each neg. sample}$$

•The weight for positive & negative samples are decided by  $n_i^+$   $n_i^-$ 

•We can keep the count from the data or we can set it manually (equivalent to duplicate data)

•The updating of approx.prior factors are affected by settings of  $n_i^+$   $n_i^-$ 



#### Final algorithm framework

•Initialize (uninformative initialization)

$$\rho_i = 0.5, \mu_{1i} = \mu_{2i}^+ = \mu_{2i}^- = 0, v_{1i} = v_{2i}^+ = v_{2i}^- = 10^6 (1 \le i \le d)$$

•Go through each data sample j, and do:

- Calculate calibrate distribution  $q^{\setminus j}(\mathbf{w}_{t_j}) = \frac{q(\mathbf{w}_{t_j})}{\prod_{k \in t_j} \mathcal{N}(w_k | \mu_{2k}^+, v_{2j}^+)^{\mathcal{I}(y_j = 1)} \mathcal{N}(w_k | \mu_{2k}^-, v_{2k}^-)^{\mathcal{I}(y_j = -1)}}$
- Update the approx. average likelihood accordingly (see details in paper)

$$v_{2k}^{+ -1} \leftarrow \frac{n_k^{+} - 1}{n_k^{+}} v_{2k}^{+ -1} + \frac{1}{n_k^{+}} v_{2k}^{+, \text{new}-1} \quad , \frac{\mu_{2k}^{+}}{v_{2k}^{+}} \leftarrow \frac{n_k^{+} - 1}{n_k^{+}} \frac{\mu_{2k}^{+}}{v_{2k}^{+}} + \frac{1}{n_k^{+}} \frac{\mu_{2k}^{+}}{v_{2k}^{+, \text{new}}} \\ v_{2k}^{- -1} \leftarrow \frac{n_k^{-} - 1}{n_k^{-}} v_{2k}^{- -1} + \frac{1}{n_k^{-}} v_{2k}^{-, \text{new}-1} \quad , \frac{\mu_{2k}^{-}}{v_{2k}^{-}} \leftarrow \frac{n_k^{-} - 1}{n_k^{-}} \frac{\mu_{2k}^{-}}{v_{2k}^{-}} + \frac{1}{n_k^{-}} \frac{\mu_{2k}^{-}}{v_{2k}^{-, \text{new}}}$$

• If N\_batch samples has been processed, update weight prior factors(see details in paper) Bernoulli $(s_i|\rho_i)\mathcal{N}(w_i|\mu_{1i},v_{1i})$   $(1 \le i \le d)$  D16



When we finish training...

•How to do feature selection?

- Check the posterior feature selection indicator
- choose feature with weight  $\left\{ j \mid q(s_j = 1) > \frac{1}{2} \right\}$
- •How to do predict?
  - Simply prediction: just use the posterior mean of selected feature weight(what we pick for experiments)
  - Bayesian prediction: use both the posterior mean and variance, final predictions are given as a distribution (need sampling trick)



Dataset and Baseline

#### •Online Ad click dataset Gemini and BrightRoll from Yahoo! Platform

• Split in three groups(see details in paper)

	Train size	Test size	Num of features
GROUP1	9.7M	553.6M + 878.7M+ 546.8M	1,074,917
GROUP2	1.8M	116.0M + 110.2M+ 133.7M	204,327
GROUP3(unbalanced)	798,152(5004 clicks)	547,043(3688 clicks)	617,258

#### •Baselines

- FTRL-proximal: sparse online logistic regression with L1&L2 regularization(fine-tunning the optimal regularization weights)
- Vowpal Wabbit(VW): online logistic regression with all features





Fig. 1. The sparsity levels achieved by OLSS: number of selected features *v.s.* setting of  $\rho_0$ . Numbers on data points show the feature selection ratio.











# 5. Summary

1. We apply the Bayesian <u>spike and slab prior</u> on general binary classification problems where the sparsity helps the feature selection over large number of feature.

2. Based on the *Stochastic Expectation Propagation* framework, we developed an online inference algorithm, which could handle large-scale size data efficiently by giving closed form update.

3. We test the proposed method on real-word dataset, and get convincing results on both fair predictions and the sparsity of model.



Thanks for attention Q&A Time

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