## HW2 Solution

To be available at

#### ~cs5460/hw2/hw2\_soln.c

on the CADE filesystem

# Last Time

Concurrency pitfalls

- Atomic operations depend on the processor
- Multiprocessors don't even offer true globals automatically

#### Solutions

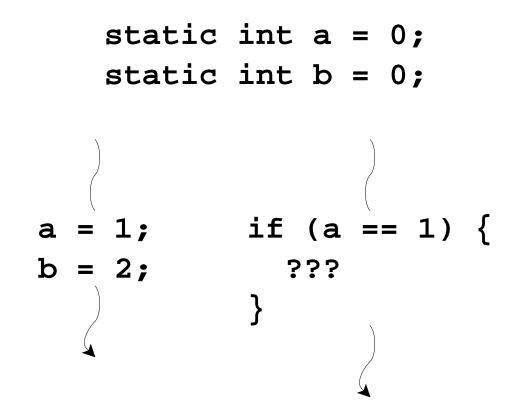
- Processor-supplied operations, e.g., compare-and-swap
- OS-supplied locks, e.g., mutexes

## Globals

When is a C global variable actually *global*? When it's consistently protected by a lock.

static int counter; ... lock(); counter++; unlock();

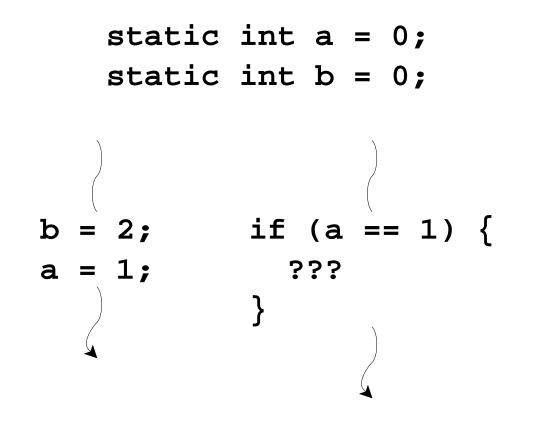
#### Globals



If the left thread reaches ???, is b necessarily 2?

No.

#### Globals



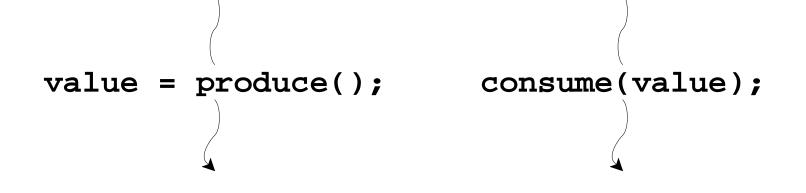
If the left thread reaches ???, is b necessarily 2?

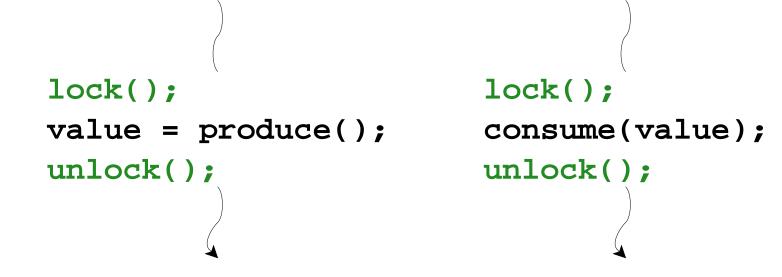
No.

 $\Rightarrow$  use a lock around accesses of  ${\bf a}$  and  ${\bf b}$ 

## General Points about Shared Data and Concurency

- **1.** Protect shared globals with a lock.
- **2.** No, really, use a lock!
- **3.** I'm not kidding about using locks.





```
lock();
value = produce();
unlock();
```

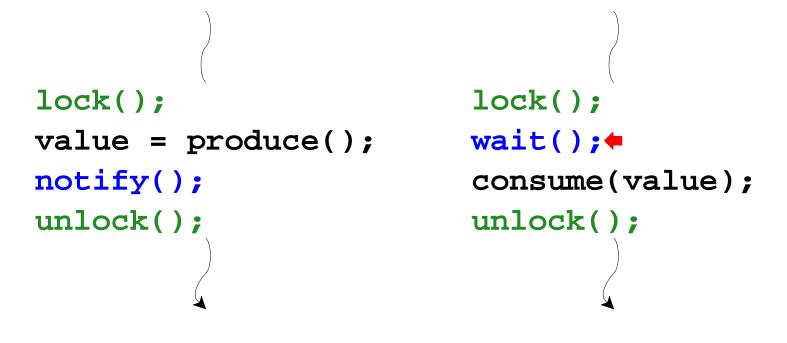
```
lock();
while (!value) {
    unlock(); lock();
}
consume(value);
unlock();
```

```
lock();
value = produce();
unlock();
```

```
lock();
wait();
consume(value);
unlock();
```

```
lock();
value = produce();
notify();
unlock();
```

```
lock();
wait();
consume(value);
unlock();
```



waiting temporarily releases the lock

#### Mutexes + Conditions

#### See prod\_cons.c and prod\_cons\_2.c

The while plus pthread\_cond\_wait pattern avoids a race on starting wait versus delivering signal

## Semaphores

A *semaphore* encapsulates the mutex + condition pattern

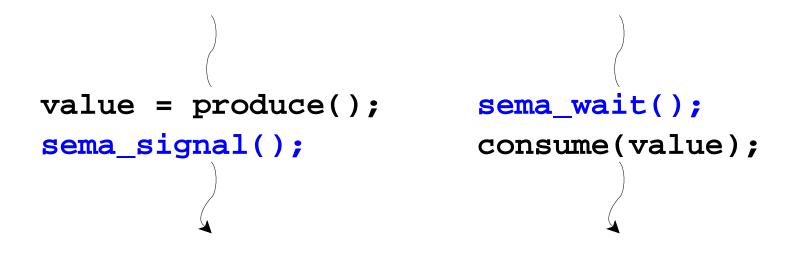
• sema\_wait()

a.k.a. P()

• sema\_signal()

a.k.a. V(), sema\_post()

## Producer & Consumer with a Semaphore



Unlike conditions, a semaphore signal is retained until waited on

#### Semaphores

See sema\_prod\_cons.c and sema\_prod\_cons\_2.c

## Binary vs. Counting Semaphores

A *binary semaphore* holds a single signal

A *counting semaphore* holds multiple signals to be consumed by multiple waits

#### Semaphores as Plain Locks

mutex\_lock(m);
critical region
mutex\_unlock(m);

semap\_wait(s);
critical region
sema\_signal(s);

# Monitors

What happens if you get it backward?

sema\_signal(s);
critical region
sema\_wait(s);

A *monitor* is a language construct that helps avoid such mistakes

synchronized {
 critical region
}

(see book for more details)

## **Multiple Data**

Two different objects:

```
static thing_t a_obj;
static thing_t b_obj;
```

One lock or two?

- If a\_obj and b\_obj are always used together, one lock is probably best.
- If a\_obj and b\_obj are often used independently, then give them separate locks.

In the second case, you sometimes need both locks...

## **Multiple Locks**

```
sema_wait(A);
sema_wait(B);
swap(a_obj, b_obj);
sema_signal(B);
sema_signal(A);
```

```
sema_wait(B);
sema_wait(A);
swap(b_obj, a_obj);
sema_signal(A);
sema_signal(B);
```

To avoid deadlock when acquiring multple locks:

- Establish a total order on all locks
- Always acquire the locks in order