

# Lecture 14: Interconnection Networks

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- Topics: dimension vs. arity, deadlock

# Interconnection Networks

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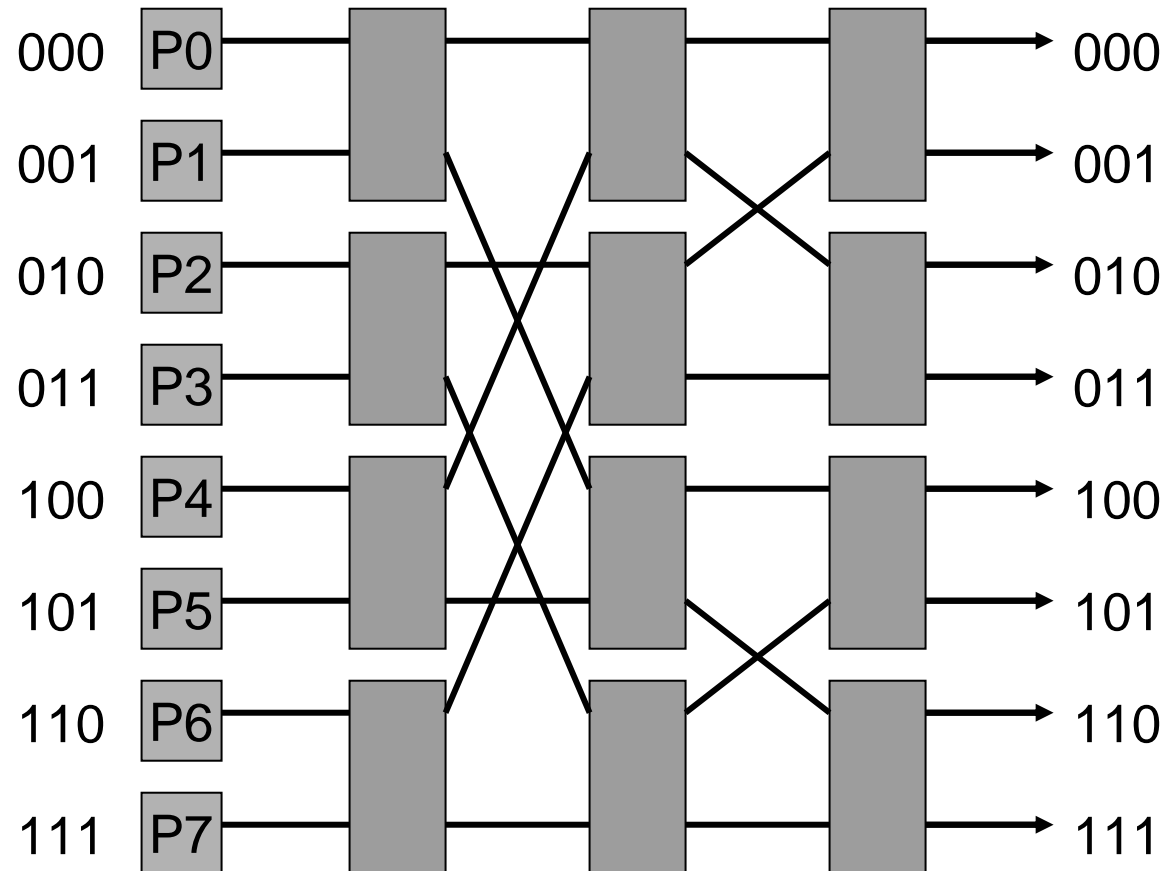
- Recall: fully connected network, arrays/rings, meshes/tori, trees, butterflies, hypercubes
- Consider a k-ary d-cube: a d-dimension array with k elements in each dimension, there are links between elements that differ in one dimension by 1 (mod k)
- Number of nodes  $N = k^d$

Number of switches	: N	Avg. routing distance:	$d(k-1)/2$
Switch degree	: $2d$	Diameter	: $d(k-1)$
Number of links	: $Nd$	Bisection bandwidth	: $2wk^{d-1}$
Pins per node	: $2wd$		

Should we minimize or maximize dimension?

# Butterfly Network

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# Bisection Bandwidth

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Break the  $k^d$  nodes into two groups such that all elements  
in group-1 are of the form:  $[0 - k/2-1] [*][*]...[*]$   
in group-2 are of the form:  $[k/2 - k] [*][*]...[*]$

- Each node has an edge to other nodes that differ in only one dimension by one
- Any node in group-1 differs from any node in group-2 in at least the first dimension – hence, any edge from group-1 to group-2 is an edge that connects nodes that are identical in  $d-1$  dimensions and differ in the first dimension by 1
- If we fix the co-ordinates of the  $d-1$  dimensions, we can identify two edges:  $[0, i_1, \dots, i_{d-1}] - [k-1, i_1, \dots, i_{d-1}]$  and  $[k/2-1, i_1, \dots, i_{d-1}] - [k/2, i_1, \dots, i_{d-1}]$  : there are totally  $2k^{d-1}$  edges

# Dimension

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- For a fixed machine size  $N$ , low-dimension networks have significantly higher latencies for a packet – scalable machines should employ high dimensionality (high cost!)
- For a fixed number of pins, message latency decreases at first, then increases (as we increase dimensionality)
- What if we keep constant bisection bandwidth?
- Lower dimensions also reduce wire length

Number of switches :  $N$   
Switch degree :  $2d$   
Number of links :  $Nd$   
Pins per node :  $2wd$

Avg. routing distance:  $d(k-1)/2$   
Diameter :  $d(k-1)$   
Bisection bandwidth :  $2wk^{d-1}$   
 $N = k^d$

# Routing

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- Deterministic routing: given the source and destination, there exists a unique route
- Adaptive routing: a switch may alter the route in order to deal with unexpected events (faults, congestion) – more complexity in the router vs. potentially better performance
- Example of deterministic routing: dimension order routing: send packet along first dimension until destination co-ord (in that dimension) is reached, then next dimension, etc.
- Routing strategies: source-based, arithmetic-(destination) based, table-driven

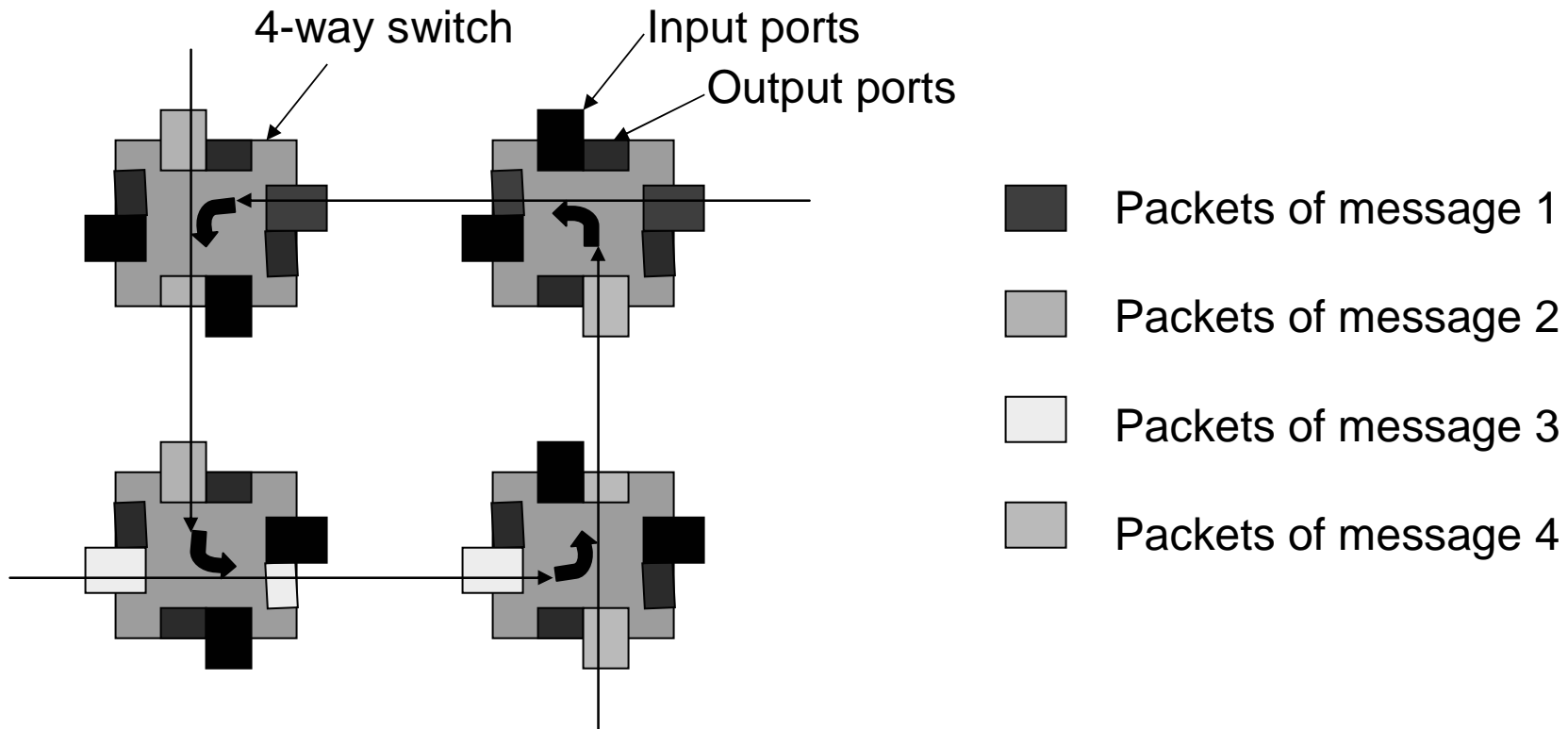
# Deadlock

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- Deadlock happens when there is a cycle of resource dependencies – a process holds on to a resource (A) and attempts to acquire another resource (B) – A is not relinquished until B is acquired

# Deadlock Example

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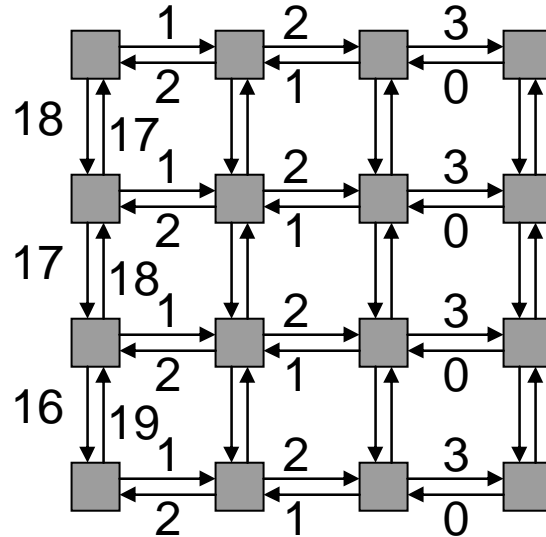
Each message is attempting to make a left turn – it must acquire an output port, while still holding on to a series of input and output ports



# Deadlock-Free Proofs

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- Number edges and show that all routes will traverse edges in increasing (or decreasing) order – therefore, it will be impossible to have cyclic dependencies
- Example: k-ary 2-d array with dimension routing: first route along x-dimension, then along y



# Breaking Deadlock I

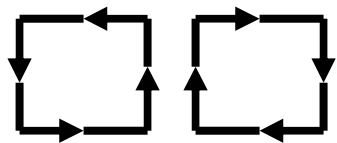
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- The earlier proof does not apply to tori because of wraparound edges
- Partition resources across multiple virtual channels
- If a wraparound edge must be used in a torus, travel on virtual channel 1, else travel on virtual channel 0

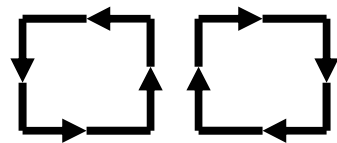
# Breaking Deadlock II

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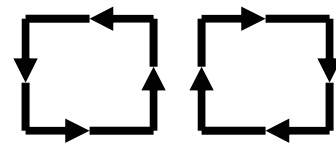
- Consider the eight possible turns in a 2-d array (note that turns lead to cycles)
- By preventing just two turns, cycles can be eliminated
- Dimension-order routing disallows four turns
- Helps avoid deadlock even in adaptive routing



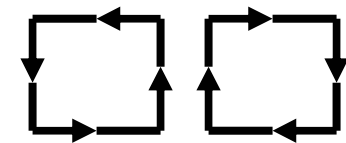
West-First



North-Last



Negative-First



Can allow  
deadlocks

# Title

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- Bullet