#### Lecture 14: Interconnection Networks

• Topics: dimension vs. arity, deadlock

- Recall: fully connected network, arrays/rings, meshes/tori, trees, butterflies, hypercubes
- Consider a k-ary d-cube: a d-dimension array with k elements in each dimension, there are links between elements that differ in one dimension by 1 (mod k)
- Number of nodes  $N = k^d$

Number of switches :	Avg. routing distance:
Switch degree :	Diameter :
Number of links :	Bisection bandwidth :
Pins per node :	Switch complexity :

Should we minimize or maximize dimension?

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Number of switches: N

Switch degree

Number of links

Pins per node

Avg. routing distance: Diameter : Bisection bandwidth : Switch complexity : d(k-1)/2 d(k-1) 2wk<sup>d-1</sup> (2d + 1)<sup>2</sup>

(with no wraparound)

Should we minimize or maximize dimension?

: 2d + 1

: Nd

: 2wd

Break the k<sup>d</sup> nodes into two groups such that all elements in group-1 are of the form: [0 - k/2-1] [\*][\*]...[\*] in group-2 are of the form: [k/2 - k] [\*][\*]...[\*]

- Each node has an edge to other nodes that differ in only one dimension by one
- Any node in group-1 differs from any node in group-2 in at least the first dimension – hence, any edge from group-1 to group-2 is an edge that connects nodes that are identical in d-1 dimensions and differ in the first dimension by 1
- If we fix the co-ordinates of the d-1 dimensions, we can identify two edges:  $[0, i_1, \dots, i_{d-1}] [k-1, i_1, \dots, i_{d-1}]$  and  $[k/2-1, i_1, \dots, i_{d-1}] [k/2, i_1, \dots, i_{d-1}]$ : there are totally  $2k^{d-1}$  edges

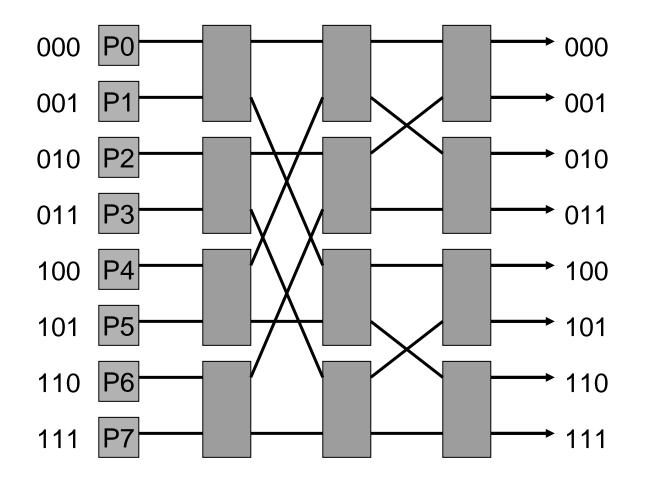
### Dimension

- For a fixed machine size N, low-dimension networks have significantly higher latencies for a packet scalable machines should employ high dimensionality (high cost!)
- For a fixed number of pins, message latency decreases at first, then increases (as we increase dimensionality)
- What if we keep constant bisection bandwidth?

Number of switches :	Ν
Switch degree :	2d+1
Number of links :	Nd
Pins per node :	2wd

Avg. routing distance:d(k-1)/2Diameter:d(k-1)Bisection bandwidth: $2wk^{d-1}$ Switch complexity: $(2d + 1)^2$  5N = k^d

#### Butterfly Network



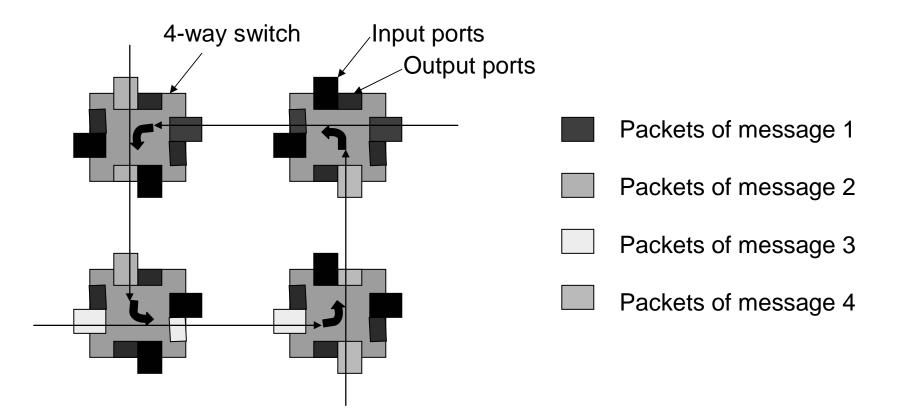
# Routing

- Deterministic routing: given the source and destination, there exists a unique route
- Adaptive routing: a switch may alter the route in order to deal with unexpected events (faults, congestion) more complexity in the router vs. potentially better performance
- Example of deterministic routing: dimension order routing: send packet along first dimension until destination co-ord (in that dimension) is reached, then next dimension, etc.

#### Deadlock

 Deadlock happens when there is a cycle of resource dependencies – a process holds on to a resource (A) and attempts to acquire another resource (B) – A is not relinquished until B is acquired

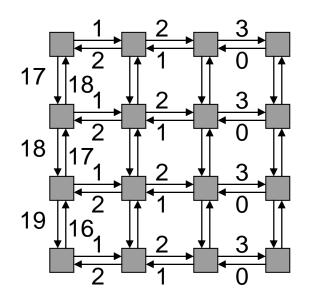
## Deadlock Example



Each message is attempting to make a left turn – it must acquire an output port, while still holding on to a series of input and output ports

#### **Deadlock-Free Proofs**

- Number edges and show that all routes will traverse edges in increasing (or decreasing) order therefore, it will be impossible to have cyclic dependencies
- Example: k-ary 2-d array with dimension routing: first route along x-dimension, then along y

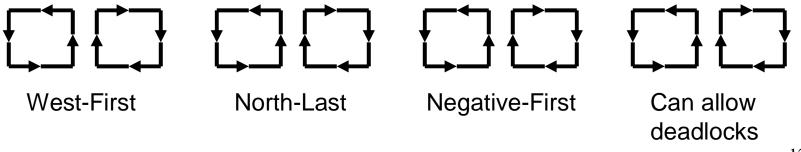


## **Breaking Deadlock I**

- The earlier proof does not apply to tori because of wraparound edges
- Partition resources across multiple virtual channels
- If a wraparound edge must be used in a torus, travel on virtual channel 1, else travel on virtual channel 0

## **Breaking Deadlock II**

- Consider the eight possible turns in a 2-d array (note that turns lead to cycles)
- By preventing just two turns, cycles can be eliminated
- Dimension-order routing disallows four turns
- Helps avoid deadlock even in adaptive routing



# Title

• Bullet