• Topics: memory scheduling, refresh, memory trends

• For the following access stream, estimate the finish times for each access with the following scheduling policies:

Req	Time of arrival	Open	Closed	Oracular
Х	0 ns	40	40	40
Y	10 ns	100	100	100
X+1	100 ns	160	160	160
X+2	200 ns	220	240	220
Y+1	250 ns	310	300	290
X+3	300 ns	370	360	350

Note that X, X+1, X+2, X+3 map to the same row and Y, Y+1 map to a different row in the same bank. Ignore bus and queuing latencies. The bank is precharged at the start.

- For the following access stream, estimate the finish times for each access with the following scheduling policies:
 - Req Time of arrival Open Closed Oracular
 - X 10 ns
 - X+1 15 ns
 - Y 100 ns
 - Y+1 180 ns
 - X+2 190 ns
 - Y+2 205 ns

Note that X, X+1, X+2, X+3 map to the same row and Y, Y+1 map to a different row in the same bank. Ignore bus and queuing latencies. The bank is precharged at the start.

• For the following access stream, estimate the finish times for each access with the following scheduling policies:

Req	Time of arrival	Open	Closed	Oraculai
Х	10 ns	50	50	50
X+1	15 ns	70	70	70
Y	100 ns	160	140	140
Y+1	180 ns	200	220	200
X+2	190 ns	260	300	260
Y+2	205 ns	320	240	320

Note that X, X+1, X+2, X+3 map to the same row and Y, Y+1 map to a different row in the same bank. Ignore bus and queuing latencies. The bank is precharged at the start. ** A more sophisticated oracle can do even better.

Address Mapping Policies

- Consecutive cache lines can be placed in the same row to boost row buffer hit rates
- Consecutive cache lines can be placed in different ranks to boost parallelism
- Example address mapping policies: row:rank:bank:channel:column:blkoffset

row:column:rank:bank:channel:blkoffset

- A single bus is used for reads and writes
- The bus direction must be reversed when switching between reads and writes; this takes time and leads to bus idling
- Hence, writes are performed in bursts; a write buffer stores pending writes until a high water mark is reached
- Writes are drained until a low water mark is reached

- FCFS: Issue the first read or write in the queue that is ready for issue
- First Ready FCFS: First issue row buffer hits if you can
- Close page -- early precharge
- Alternate between reads and writes
- Squeeze in refreshes where possible
- Stall Time Fair: First issue row buffer hits, unless other threads are being neglected

- For every 64-bit word, can add an 8-bit code that can detect two errors and correct one error; referred to as SECDED – single error correct double error detect
- A rank is now made up of 9 x8 chips, instead of 8 x8 chips
- Stronger forms of error protection exist: a system is chipkill correct if it can handle an entire DRAM chip failure

- Every DRAM cell must be refreshed within a 64 ms window
- A row read/write automatically refreshes the row
- Every refresh command performs refresh on a number of rows, the memory rank is unavailable during that time
- A refresh command is issued by the memory controller once every 7.8us on average

 Consider a single 4 GB memory rank that has 8 banks. Each row in a bank has a capacity of 8KB. On average, it takes 40ns to refresh one row. Assume that all 8 banks can be refreshed in parallel. For what fraction of time will this rank be unavailable because of refresh? How many rows are refreshed with every refresh command?

 Consider a single 4 GB memory rank that has 8 banks. Each row in a bank has a capacity of 8KB. On average, it takes 40ns to refresh one row. Assume that all 8 banks can be refreshed in parallel. For what fraction of time will this rank be unavailable because of refresh? How many rows are refreshed with every refresh command?

The memory has 4GB/8KB = 512K rows There are 8K refresh operations in one 64ms interval. Each refresh operation must handle 512K/8K = 64 rows Each bank must handle 8 rows One refresh operation is issued every 7.8us and the memory is unavailable for 320ns, i.e., for 4% of time.

Modern Memory Systems I



Modern Memory Systems II



- The link into the processor is narrow and high frequency
- The Scalable Memory Buffer chip is a "router" that connects to multiple DDR channels (wide and slow)
- Boosts processor pin bandwidth and memory capacity
- More expensive, high power

- Processor pin count is not increasing; can't add much load per wire; SMB-like approaches help address the capacity/bw trade-off
- High Bandwidth Memory uses wiring on a silicon substrate (interposer) to achieve high bandwidth; uses 3D-stacked memory chips to increase capacity on the substrate



- DRAM cell scaling is expected to slow down
- Emerging memory cells are expected to have better scaling properties and eventually higher density: phase change memory (PCM), spin torque transfer (STT-RAM), etc. – see Intel Optane Memory
- PCM: heat and cool a material with elec pulses the rate of heat/cool determines if the material is crystalline/amorphous; amorphous has higher resistance (i.e., no longer using capacitive charge to store a bit)
- Advantages: non-volatile, high density, faster than Flash/disk
- Disadvantages: poor write latency/energy, low endurance ¹⁵