

## CS7960 L22 : GPU | Sorting

### GPU

#### Parallel processor

- Many cores
- Small memory

#### memory transfer overhead

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#### Sorting:

Input: Large array  $A = \langle a_1, a_2, \dots, a_n \rangle$

Output  $B = \langle b_1, b_2, \dots, b_n \rangle$

- $\mu(a_i) = b_j$  exists
- $b_j \leq b_{\{j+1\}}$

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#### Data driven sorting?

- insertion sort?  
 $O(n^2)$   
(choose one and place in correct spot)
- quick sort?  
 $O(n \log n)$   
(need splitter: median hard, otherwise varies size...)
- heap sort?  
 $O(n \log n)$   
(need to maintain heap data structure, hard on GPU)
- radix sort?  
 $O(nk)$  (for  $k$  digit w/ constant bits)  
lengths of each digit category uncontrollable length.

<hard to make highly parallel>

#### Data Independent sorting

- bubble sort?  
 $O(n^2)$   
(compare all neighbors)  
very parallelizable, but takes  $n$  rounds to move point from 1 to

n

- merge sort?  
 $O(n \log n)$   
 (divide + conquer + join)  
 join step very sequential :(
- bitonic sort  
 (divide + conquer + join)  
 join step parallel !!!

<will also hybridize merge+bubble...>

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Bitonic Sort:

Bitonic sequence:

- increasing,                   1 2 4 6 8 11
  - decreasing,                   9 7 4 3 2 1
  - increasing then decreasing, or   1 4 6 9 3 2
  - decreasing then increasing.    9 5 2 3 4 6
- (at most one local maxima/minima)

BitonicSplit(A):

Input: 1 bitonic sequence A size n

Output: 1 increasing (sorted) sequence B size n

```

for h = log n to 1
  for i = 1 to n/2^h PARDO
    for j = 0 to 2^{h-1} PARDO
      min(A[i + (2j)*(n/2^h)], A[i + (2j+1)(n/2^h)]) -> B[i +
(2j)*(n/2^h)]
      max(A[i + (2j)*(n/2^h)], A[i + (2j+1)(n/2^h)]) -> B[i + (2j+1)
(n/2^h)]

```

Example:

```

24 20 15 9 4 2 5 8|10 11 12 13 22 30 32 45
10 11 12 9|4 2 5 8|24 20 15 13|22 30 32 45
4 2|5 8|10 11|12 9|22 20|15 13|24 30|32 45
4|2|5 8|10 9|12 11|15 13|22 20|24 30|32 45
2 4 5 8 9 10 11 12 13 15 20 22 24 30 32 45

```

How to get a bitonic sequence?

```
for h = 1 to log n
  for i = 1 to n/2^h PARDO
    for j = 0 to 2^{h-1} PARDO
      BitonicSplit(A[i + (2j)(n/2^h), i + (2j+2)(n/2^h) - 1]) //
      (reverse second half)
```

- sets of size 2 are bitonic
- let S be an ascending sorted set  
let T be a descending sorted set  
S cat T is bitonic
- run bitonic sort of sets of doubled size for log n rounds

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BitonicSplit on all pairs -> sort all pairs  
BitonicSplit on all quads (reverse second pair) -> sort all quads  
...  
BitonicSplit on list (reverse second half) -> sorted list

$O(\log n)$  rounds of Bitonic split  
Each Bitonic split takes  $O(\log n)$  rounds

$O(\log^2 n)$  parallel time  
 $O(n \log^2 n)$  work

Fine-grain parallelism:

- core of each operation is a compare.
- data independent

For several years, this was fastest GPU sort!  
What are the weak points of this?  
How can it be improved?

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Hybrid (bucket/quick + merge sort)

Sintorn + Assarsson 08  
(beats bitonic by factor 2-3)  
takes advantage of advanced architecture of GPU (GeForce 8800)

1. Create  $L$  sub-lists using  $L-1$   $\{l_1, l_2, \dots, l_{L-1}\}$  pivotes so  $p$  in  $L_i$  has  $l_i < p \leq l_{i+1}$
2. Move each  $L_i$  to separate processor group
3. Merge Sort on each list  $L_i$

details:

(1) three proposed methods:

(a) bucket sort (two-rounds)

i : choose  $L-1$  pivots by linear interpolation  $[\min, \max]$   
 (random sample may work better, distribution

independent)

ii : build histogram w/ AtomicInc on buckets

iii: re-linear interpolate based on histogram

(again I think random sample may work better, more

general)

(b) Use NVidia histogram functionality to help w/ splits.

(c) Run  $\log(L)$  rounds of quick sort by choosing random pivots

(d) other option: run multi-selection sort we discussed in class  
 or just  $\log(L)$  median operations in  $O(N)$  time each

Note: assigning a point  $p$  to a pivot can be done in parallel, but takes  $O(\log L)$  (binary search on  $\{l_i\}_i$ ). Perhaps can be done quicker with clever bit-shifting....

(2) Use local hierarchy of GPU to move to sub-hierarchies on GPU each  $L$  of roughly the same size.

Importance of same size, otherwise, when last is running, others will be idle.

(3)

1. break to sets of size 4

2. run special "kernel" to sort sets of size 4

3. merge pairs of sets

(for most of run, many more sets than processors, so highly parallel)

4. eventually  $p$  processors in group, and  $< p$  lists left to merge (lose some parallelism, but oh, well, did pretty well).

Work =  $O(n \log n)$

PTime :

(1) =  $O(\log L)$

(a) 2 rounds of  $O(\log L)$  time to assign

(c)  $\log L$  rounds of finding median (and counting)

\*  $O(\log n \log \log n)$  to find median

but heuristic (random split) only takes  $O(1)/\text{round}$

(2) =  $O(\log L)$  (each list of size roughly  $N/L$ ) (but could be  $N$  !)

(3) =  $O(n/L)$  since last round one processor needs to run a merge on two lists.

=  $O(n/L + \log L)$  optimal for  $L = n \rightarrow (\log n)$

but that requires (1) to complete sort! ...L restricted by num processors

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Odd-Even Transition Merge Sort:

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Odd-Even Transition Sort:

for  $h = 1$  to  $n/2$

for  $i=1$  to  $n/2$  PARDO

$\min(A[2i-1], A[2i]) \rightarrow A[2i-1]$

$\max(A[2i-1], A[2i]) \rightarrow A[2i]$

for  $i=1$  to  $n/2-1$  PARDO

$\min(A[2i], A[2i+1]) \rightarrow A[2i]$

$\max(A[2i], A[2i+1]) \rightarrow A[2i+1]$

$O(n)$  Ptime,  $O(n^2)$  Work

Way to make this

-  $O(\log^2 n)$  Ptime

-  $O(n \log^2 n)$  Work

- fine-grained

- data independent

1. Grow sorted sub-pieces

2. Join takes  $O(\log m)$  for sorted sets of size  $m$

"sorting network"