

Nearest Neighbor Classifiers

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The geometric view of data

We've already talked about representing a data point as a vector:

- ▶ The **length** of the vector is the total number of features
- ▶ Each **element** in the vector is the associated feature value

Once we've done this, we can think about data as points in high-dimensional space.

This enables us to use tools from **linear algebra** to think about learning problems:

- ▶ Distance between examples \leftarrow [this lecture](#)
- ▶ Linear transformations
- ▶ Projections onto subspaces

Vectors and Matrices

We will often treat a data point as a vector. If there are D -many features, then $\mathbf{x} = \langle x_1, \dots, x_D \rangle$ can represent one example.

A data set of N examples can be represented as a matrix \mathbf{X} defined so that $X_{n,d}$ is the d th feature value for the n th example.

Some things that are useful to know about vectors and matrices:

- ▶ Addition and subtraction of vectors/matrices is element-wise
- ▶ The **norm** of a vector is its length: $\|\mathbf{x}\| = \sqrt{\sum_{d=1}^D x_d^2}$
- ▶ The **dot product** of two vectors is the sum of the product of their components: $(\mathbf{x} \cdot \mathbf{y}) = \sum_{d=1}^D x_d y_d$
A **dot product** can be thought of as a measure of similarity. Two orthogonal vectors have a dot product of zero. Two parallel ones have a really high dot product.
- ▶ The norm can be expressed as $\|\mathbf{x}\| = \sqrt{\mathbf{x} \cdot \mathbf{x}}$

Vectors and Matrices, continued...

Matrices with M rows and N columns are written as $\mathbf{A} \in \mathbb{R}^{M \times N}$.

- ▶ $\mathbf{A} \in \mathbb{R}^{L \times M}$ can be multiplied by $\mathbf{B} \in \mathbb{R}^{M \times N}$ to yield $\mathbf{C} \in \mathbb{R}^{L \times N}$. Elements are defined by: $C_{l,n} = \sum_m A_{l,m} B_{m,n}$
- ▶ The identity matrix is square with zeros everywhere except along the diagonal, which has ones. It is denoted \mathbf{I} , or sometimes \mathbf{I}_D to denote the dimensionality. In matlab, this is `eye(D)`.
- ▶ The transpose operator (eg., \mathbf{A}^T) flips a $M \times N$ matrix into a $N \times M$ matrix. In matlab, this is `A'`.
- ▶ So if a vector \mathbf{x} is a $D \times 1$ matrix, then $\mathbf{x}^T \mathbf{x}$ is a scalar, but $\mathbf{x} \mathbf{x}^T$ is a matrix.

Reminder: Euclidean distance

Given $\mathbf{x} = \langle x_1, x_2, \dots, x_D \rangle$ and $\mathbf{y} = \langle y_1, y_2, \dots, y_D \rangle$, the **Euclidean distance** between \mathbf{x} and \mathbf{y} is defined by:

$$\begin{aligned} \|\mathbf{x} - \mathbf{y}\| &= \sqrt{\sum_{d=1}^D (x_d - y_d)^2} \\ &= \sqrt{\sum_{d=1}^D (x_d^2 + y_d^2 - 2x_d y_d)} \\ &= \sqrt{\sum_{d=1}^D x_d^2 + \sum_{d=1}^D y_d^2 - 2 \sum_{d=1}^D x_d y_d} \\ &= \sqrt{\|\mathbf{x}\|^2 + \|\mathbf{y}\|^2 - 2\mathbf{x} \cdot \mathbf{y}} \end{aligned}$$

Embedding the play/no-play data

Y	Out	T	R	Y	$\langle \text{Out}, \text{T}, \text{R} \rangle$
P	Sunny	Low	Yes	1	$\langle ? , 0 , 1 \rangle$
N	Sunny	High	Yes	0	$\langle ? , 1 , 1 \rangle$
N	Sunny	High	No	0	$\langle ? , 1 , 0 \rangle$
P	Overcast	Low	Yes	1	$\langle ? , 0 , 1 \rangle$
P	Overcast	High	No	1	$\langle ? , 1 , 0 \rangle$
P	Overcast	Low	No	1	$\langle ? , 0 , 0 \rangle$
N	Rainy	Low	Yes	0	$\langle ? , 0 , 1 \rangle$
P	Rainy	Low	No	1	$\langle ? , 0 , 0 \rangle$



Why not just map "Sunny" to 0, "Overcast" to 1 and "Rainy" to 2?

Dealing with categorical values

Solution: map a categorical feature with K values into K binary features.

Y	Out	T	R	Y	$\langle \text{S?}, \text{O?}, \text{R?}, \text{T}, \text{R} \rangle$
P	Sunny	Low	Yes	1	$\langle 1 , 0 , 0 , 0 , 1 \rangle$
N	Sunny	High	Yes	0	$\langle 1 , 0 , 0 , 1 , 1 \rangle$
N	Sunny	High	No	0	$\langle 1 , 0 , 0 , 1 , 0 \rangle$
P	Overcast	Low	Yes	1	$\langle 0 , 1 , 0 , 0 , 1 \rangle$
P	Overcast	High	No	1	$\langle 0 , 1 , 0 , 1 , 0 \rangle$
P	Overcast	Low	No	1	$\langle 0 , 1 , 0 , 0 , 0 \rangle$
N	Rainy	Low	Yes	0	$\langle 0 , 0 , 1 , 0 , 1 \rangle$
P	Rainy	Low	No	1	$\langle 0 , 0 , 1 , 0 , 0 \rangle$

