

## Today

- ◆ Tour of optimizations
- ◆ Dataflow analysis intro

## Example 1

```
int foo (int z) {  
  x = 3 + 6;  
  y = x - 5;  
  return z * y;  
}
```

- ◆ What optimizations apply?

## Example 1

```
int foo (int z) {  
  x = 3 + 6;      => x = 9; (constant folding)  
  y = x - 5;  
  return z * y;  
}
```

- ◆ What optimizations apply?

## Example 1

```
int foo (int z) {  
  x = 3 + 6;      => x = 9; (constant folding)  
  y = x - 5;      => 9 - 5 (const prop)  
  return z * y;  
}
```

- ◆ What optimizations apply?

## Example 1

```
int foo (int z) {  
  x = 3 + 6;      => x = 9; (constant folding)  
  y = x - 5;      => 9 - 5 (const prop) => 4 (CF)  
  return z * y;  
}
```

- ◆ What optimizations apply?

## Example 1

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int foo (int z) {  
  x = 3 + 6;      => x = 9; (constant folding)  
  y = x - 5;      => 9 - 5 (const prop) => 4 (CF)  
  return z * y;   => z * 4 (CP)  
}
```

- ◆ What optimizations apply?

## Example 1

```
int foo (int z) {
  x = 3 + 6;      => x = 9; (constant folding)
  y = x - 5;     => 9 - 5 (const prop) => 4 (CF)
  return z * y;  => z * 4 (CP) => z << 2
                  (strength reduction)
}
```

- ◆ What optimizations apply?

## Example 2

```
x = a + b;
...
y = a + b;
```

- ◆ In what circumstances can (a+b) be replaced by x?
- ◆ This is common subexpression elimination (CSE) – replacing expressions that evaluate to the same value with a single variable holding the computed value

## Example 3

```
if (...) {
  x = a + b;
}

...

y = a + b;
```

- ◆ Can we change the assignment to read  $y = x$ ?

## Example 3

- ◆ Can we change the assignment to read  $y = x$ ?
- ◆ No, but we can apply partial redundancy elimination (PRE), a generalization of common subexpression elimination:

```
if (...) {
  t = a + b;
  x = t;
} else {
  t = a + b;
}

...

y := t;
```

## Example 4

```
x = y;
...
z = z + x;
```

- ◆ When can we replace x with y in the second assignment?
- ◆ This is copy propagation – replacing the occurrences of targets of direct assignments with their values

## Example 4

```
x = y**z;
...
x = 15;
```

- ◆ When can the first assignment be removed?
- ◆ This is dead assignment elimination (DAE)
  - Often cleans up after other optimizations

```
x = y          Copy prop  x = y          DAE
z = z + x      →         z = z + y      →         z = z + y
```

### Example 5

```
if (false) {  
    ...  
}
```

- ◆ When can this statement be removed?
- ◆ Dead code elimination (DCE) – another cleanup

### Example 6

- ◆ Java code:

```
a = new int [10];  
for (index = 0; index < 10; index ++) {  
    a[index] = 100;  
}
```

### Example 6

- ◆ “Lowered” Java code:

```
a = new int [10];  
for (index = 0; index < 10; index ++) {  
    if (index < 0 || index >= a.length()) {  
        throw OutOfBoundsException;  
    }  
    a[index] = 100;  
}
```

### Example 6

- ◆ “Lowered” Java code:

```
a = new int [10];  
for (index = 0; index < 10; index ++) {  
    if (index < 0 || index >= 10) {  
        throw OutOfBoundsException;  
    }  
    a[index] = 100;  
}
```

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a = new int [10];  
for (index = 0; index < 10; index ++) {  
    if (index < 0 || index >= 10) {  
        throw OutOfBoundsException;  
    }  
    a[index] = 100;  
}
```

index ∈ [0..9]

### Example 6

- ◆ “Lowered” Java code:

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a = new int [10];  
for (index = 0; index < 10; index ++) {  
    if (false) {  
        throw OutOfBoundsException;  
    }  
    a[index] = 100;  
}
```

## Example 6

◆ “Lowered” Java code:

```
a = new int [10];
for (index = 0; index < 10; index ++) {
  a[index] = 100;
}
```

## Example 7

```
p = &x;
*p = 5;
y = x + 1;
```

◆ Want to turn this into:

```
p = &x;
x = 5;
y = 6;
```

◆ This is must alias analysis – \*p must refer to x

## Example 8

```
for j = 1 to N
  for i = 1 to N
    a[i] = a[i] + b[j];
```

◆ Want to turn this into:

```
for j = 1 to N
  t = b[j];
  for i = 1 to N
    a[i] = a[i] + t;
```

◆ This is loop invariant code motion (LICM), or hoisting – executing code fewer times by moving it out of a loop, when this can be done safely

## Example 9

```
area (h,w) { return h * w; }
```

```
h = ...;
w = 4;
a = area (h,w)
```

◆ Want to turn this into:

```
h = ...;
a = h << 2;
```

◆ Requires: inlining + copy prop + DAE + strength reduction

## Optimization Themes

- ◆ Don't compute if you don't have to
  - Unused assignment elimination, DCE
- ◆ Compute at compile-time if possible
  - Constant folding, loop unrolling, inlining
- ◆ Compute it as few times as possible
  - CSE, PRE, loop invariant code motion
- ◆ Compute it as cheaply as possible
  - Strength reduction, inlining
- ◆ Enable other optimizations
  - Constant and copy prop, inlining, pointer analysis

## Overall

- ◆ Collection of relatively simple optimizations, working together and run repeatedly, can substantially improve code
- ◆ Questions
  - What order should optimizations be run in?
  - How many times should they be run?
  - Should the compiler try to optimize “stupid” code?
  - How to decide whether to apply optimizations that do not uniformly speed up code?

## Dataflow analysis: What is it?

- ◆ A common framework for expressing algorithms that compute facts about programs
  - Facts must be true across all possible executions
  - Approximation is inevitable
- ◆ Common framework is useful in order to
  - Reason about correctness of analyses
  - Communicate analyses to others
  - Compare analyses
  - Adapt techniques from one analysis to another
  - Reuse implementations

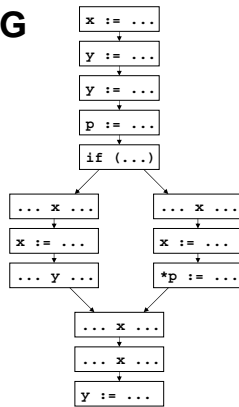
## Control Flow Graphs

- ◆ For now, we will use a Control Flow Graph (CFG) representation of programs
  - Each statement becomes a node
  - Edges between nodes represent control flow
- ◆ Later we will see other program representations
  - Variations on the CFG (e.g. CFG with basic blocks)
  - Other graph based representations

## Example CFG

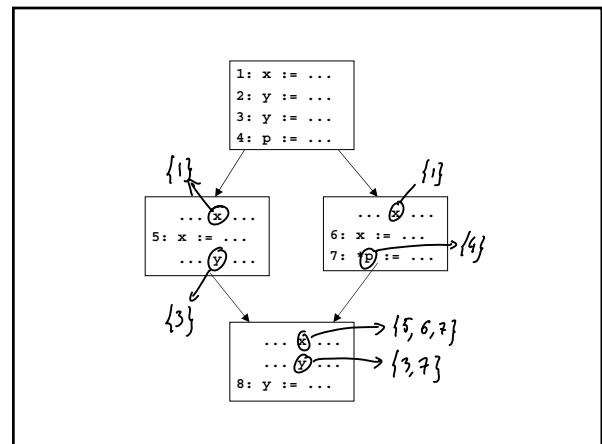
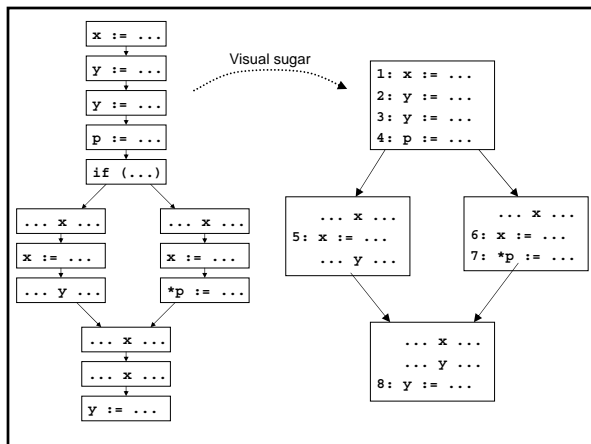
```

x := ...
y := ...
y := ...
p := ...
if (...) {
  ... x ...
  x := ...
  ... y ...
}
else {
  ... x ...
  x := ...
  *p := ...
}
... x ...
... y ...
y := ...
    
```



## Example dataflow analysis: Reaching Definitions

- ◆ For each use of a variable, determine what assignments could have set the value being read from the variable
- ◆ Useful for
  - Performing constant and copy prop
  - Detecting references to undefined variables
  - Presenting “def/use chains” to the programmer
  - Building other representations, like the DFG
- ◆ Let's try this out on an example



## Safety

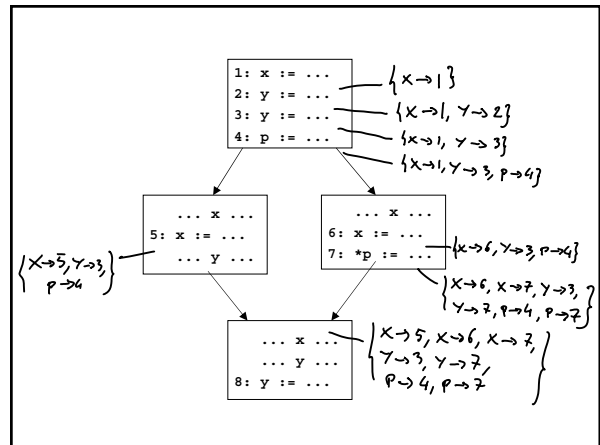
- ◆ Recall intended use of this info
  - Performing constant and copy prop
  - Detecting references to undefined variables
  - Presenting "def/use chains" to the programmer
  - Building other representations, like the DFG
- ◆ Safety criteria
  - Cannot miss any bindings
    - This would cause subsequent optimizations to change program semantics
  - Can include bindings that do not correspond to possible executions
    - But this may prevent some optimizations from firing

## Towards DFA

- ◆ What does a DFA framework do?
  - Computes information at each program point (edge) in the CFG
  - So, generalize the reaching definitions problem by stating what should be computed at each program point
- ◆ "For each program point in the CFG, compute the set of definitions (statements) that may reach that point"
- ◆ Notion of safety remains the same

## Reaching Definitions, Generalized

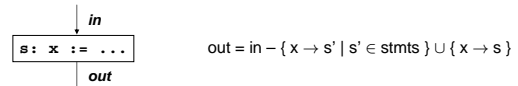
- ◆ Computed information at a program point is a set of var  $\rightarrow$  stmt bindings
  - E.g.  $\{x \rightarrow s_1, x \rightarrow s_2, y \rightarrow s_3\}$
- ◆ How do we get the previous info we wanted?
  - If a var  $x$  is used in a stmt whose incoming info is  $in$ , then:  $\{s \mid (x \rightarrow s) \in in\}$
- ◆ This is a common pattern
  - Generalize the problem to define what information should be computed at each program point
  - Use the computed information at the program points to get the original info we wanted



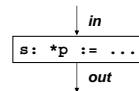
## Formalizing DFA

- ◆ Let's try to precisely express the algorithms for computing dataflow information
- ◆ We'll model DFA as solving a system of constraints
- ◆ Each node in the CFG will impose constraints relating information at predecessor and successor points
- ◆ Solution to constraints is result of analysis

## Constraints for reaching definitions

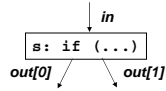


$$out = in - \{x \rightarrow s' \mid s' \in \text{stmts}\} \cup \{x \rightarrow s\}$$

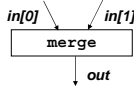


- ◆ Using may-point-to information:
 
$$out = in \cup \{x \rightarrow s \mid x \in \text{may-point-to}(p)\}$$
- ◆ Using must-point-to as well:
 
$$out = in - \{x \rightarrow s' \mid x \in \text{must-point-to}(p) \wedge s' \in \text{stmts}\} \cup \{x \rightarrow s \mid x \in \text{may-point-to}(p)\}$$

## Constraints for reaching definitions



$out[0] = in \wedge$   
 $out[1] = in$   
 more generally:  $\forall i. out[i] = in$



$out = in[0] \cup in[1]$   
 more generally:  $out = \cup_i in[i]$

## Transfer Functions

- ◆ The constraint for a statement kind  $s$  often has the form:  $out = F_s(in)$
- ◆  $F_s$  is called a transfer function (or flow function, or abstract transfer function)
  - Recall the transfer functions we looked at last week, for merge and bitwise-and in the ternary-bit domain
- ◆ Given information  $in$  before statement  $s$ ,  $F_s(in)$  returns information after statement  $s$

## Transfer Functions

- ◆ Transfer functions are a central component of a dataflow analysis
  - They state constraints on the information flowing into and out of a statement
- ◆ Today we looked at some forward transfer functions
  - They can work backwards as well

## Summary

- ◆ Dataflow analysis provides a generic framework for plugging program analyses into
- ◆ We've just scratched the surface
- ◆ Questions to think about:
  - Where do transfer functions come from?
  - Are there generic requirements for correct transfer functions?
  - How do we know if transfer functions are correct?
  - Is there always a unique solution?
  - Is dataflow analysis guaranteed to terminate?
  - What algorithms are suited to solving these systems of equations?
  - How can the CFG representation be improved to make the analysis faster?