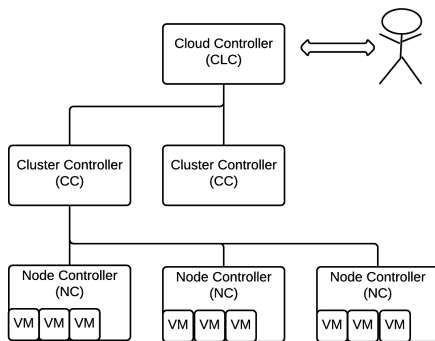


ATOM: Automated Tracking, Orchestration and Monitoring of Resource Usage in Infrastructure as a Service Systems

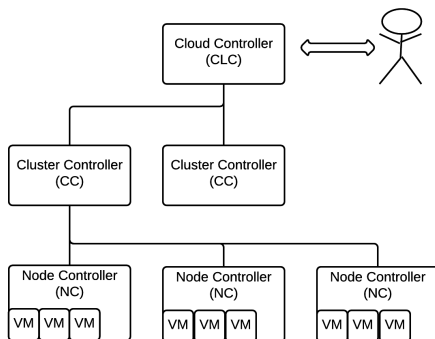
Min Du, Feifei Li

School of Computing, University of Utah

A Simplified Cloud



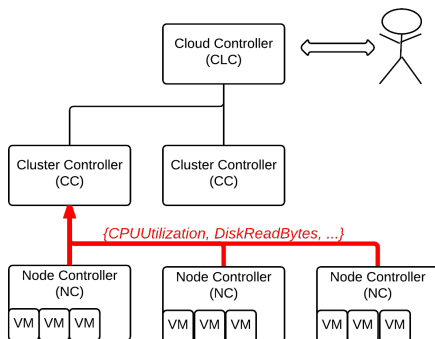
A Simplified Cloud



Monitor the Cloud

- ▶ To provide system-wide visibility
- ▶ CloudWatch (AWS/Eucalyptus)

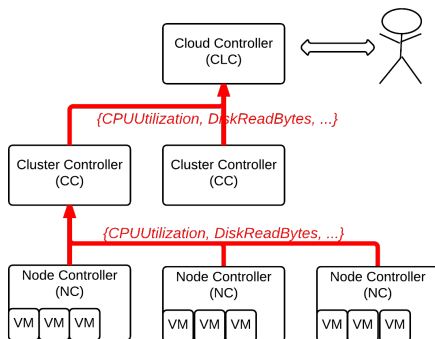
A Simplified Cloud



Monitor the Cloud

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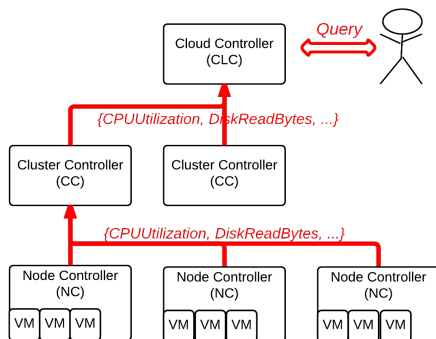
A Simplified Cloud



Monitor the Cloud

- ▶ To provide system-wide visibility
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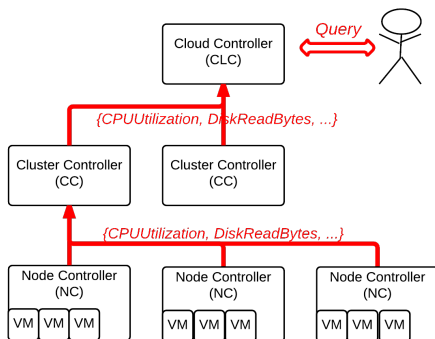
A Simplified Cloud



Monitor the Cloud

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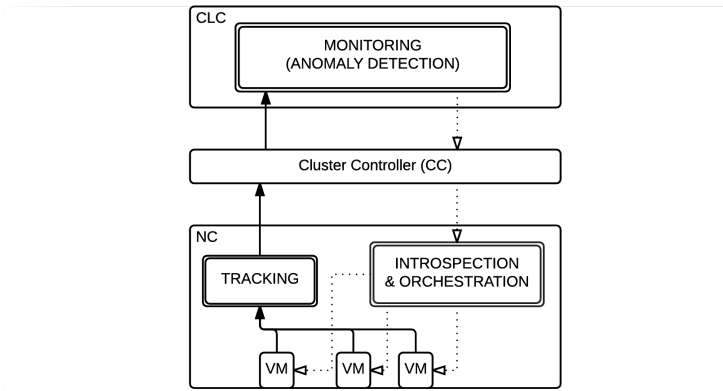
A Simplified Cloud



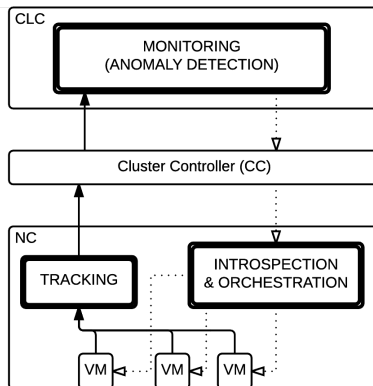
Questions

1. Monitor more efficiently?
2. Utilize the statistics for security purpose?

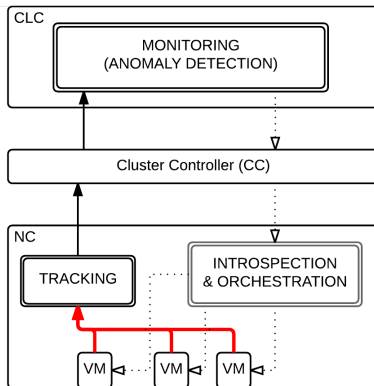
ATOM Architecture



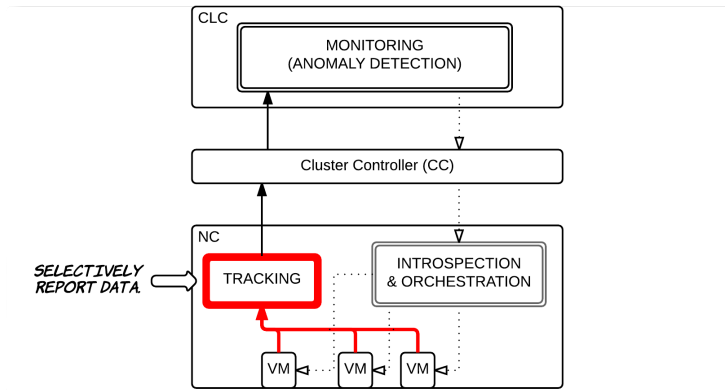
ATOM Architecture



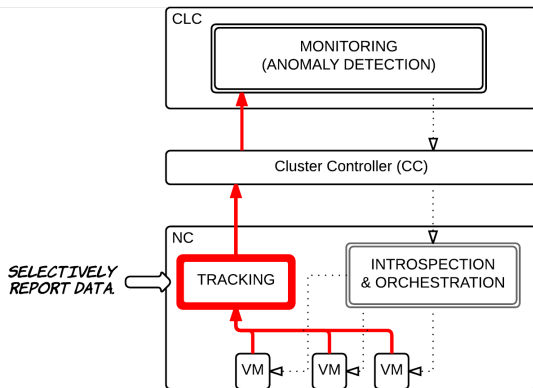
ATOM Architecture



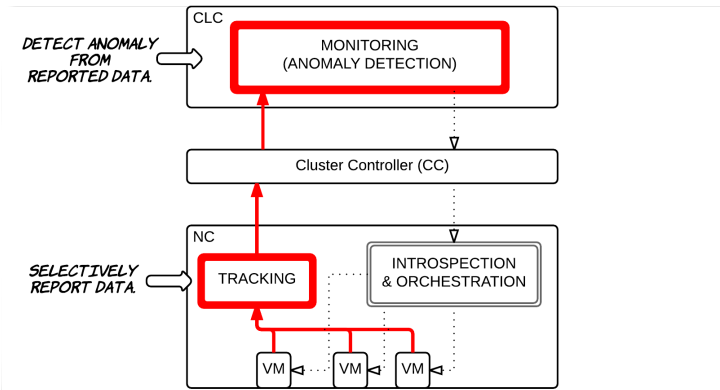
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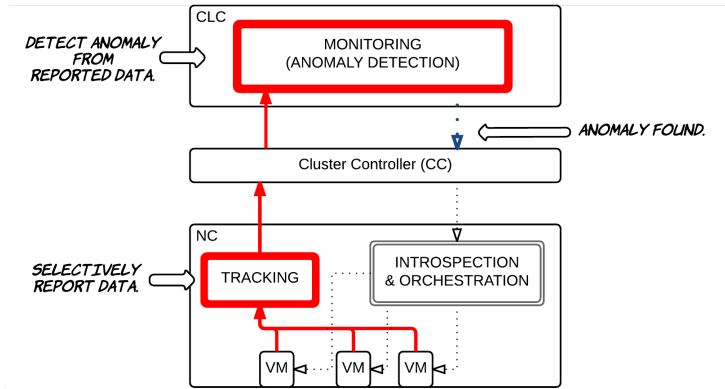
ATOM Architecture



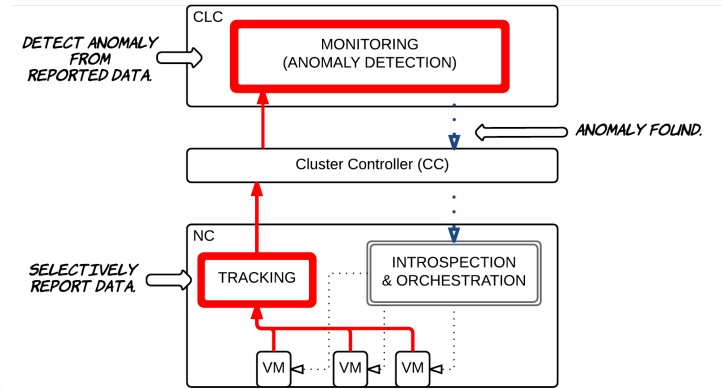
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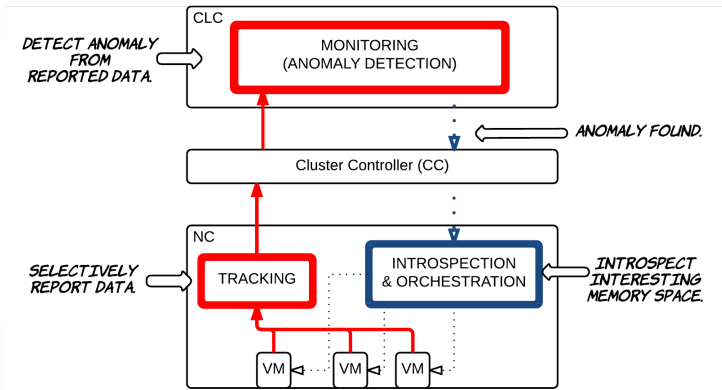
ATOM Architecture



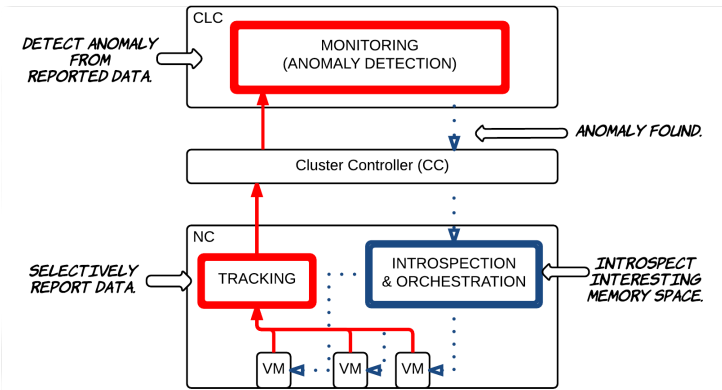
ATOM Architecture



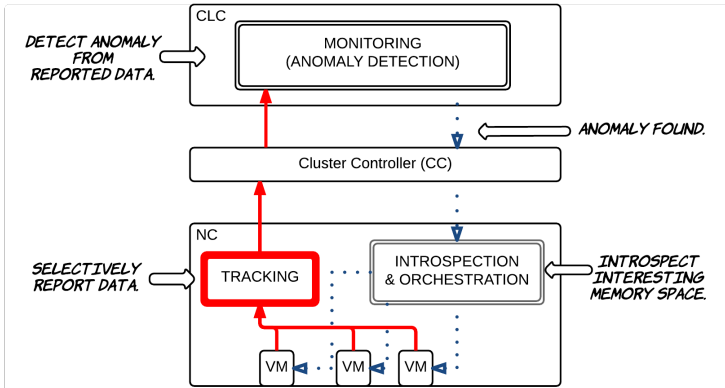
ATOM Architecture



ATOM Architecture

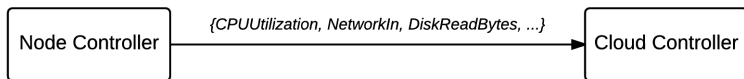


Tracking Component

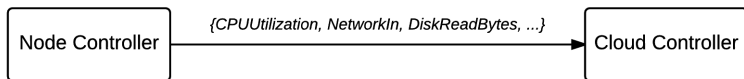


Tracking Component

Tracking Component

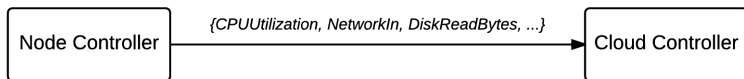


Tracking Component



What if a small error Δ is allowed?

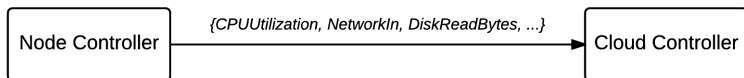
Tracking Component



What if a small error Δ is allowed?

- ▶ Sequence: `{0, 6, 0, 6, 0, 6, ...}`; $\Delta = 4$

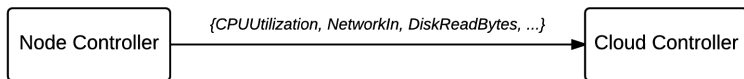
Tracking Component



What if a small error Δ is allowed?

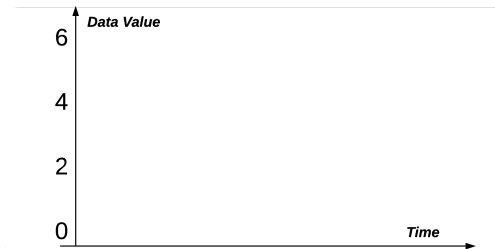
- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:

Tracking Component

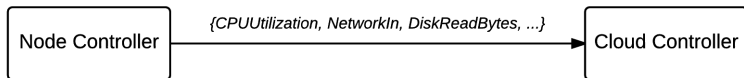


What if a small error Δ is allowed?

- ▶ Sequence: {0, 6, 0, 6, 0, 6, ...}; $\Delta = 4$
- ▶ A naive way:

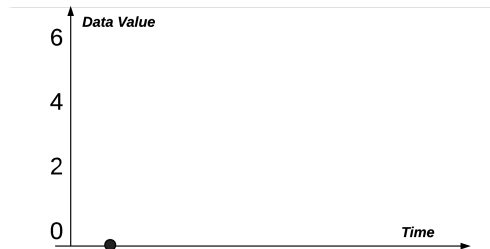


Tracking Component

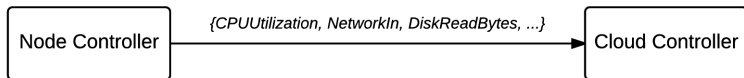


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:

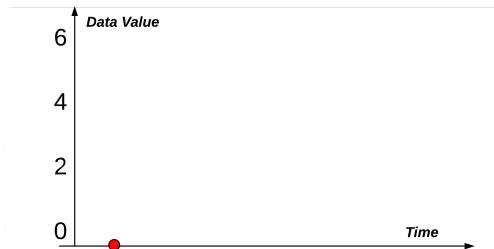


Tracking Component

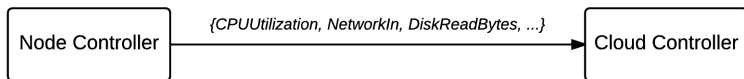


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:

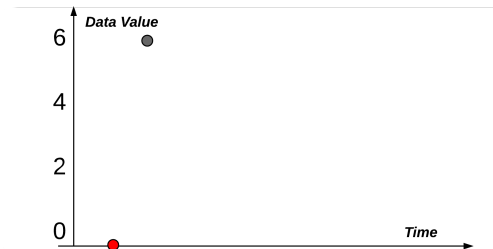


Tracking Component

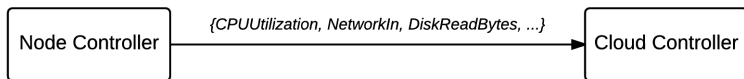


What if a small error Δ is allowed?

- ▶ Sequence: {0, 6, 0, 6, 0, 6, ...}; $\Delta = 4$
- ▶ A naive way:

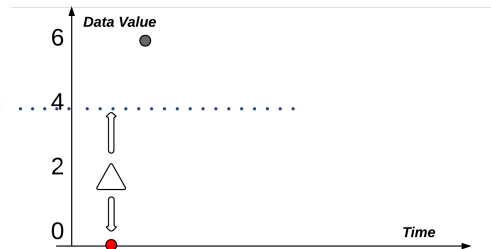


Tracking Component

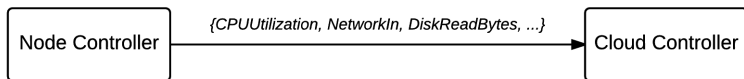


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:

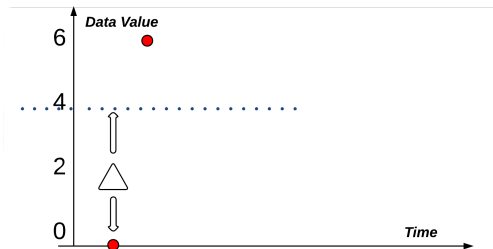


Tracking Component

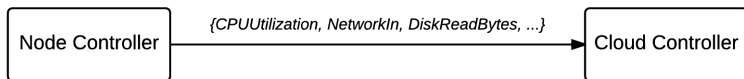


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:

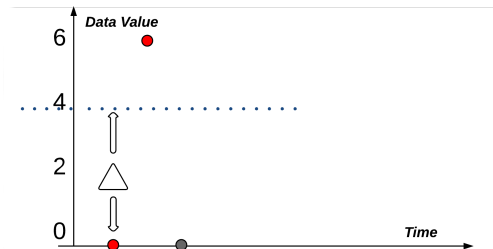


Tracking Component

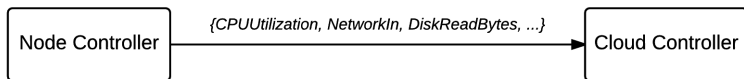


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:

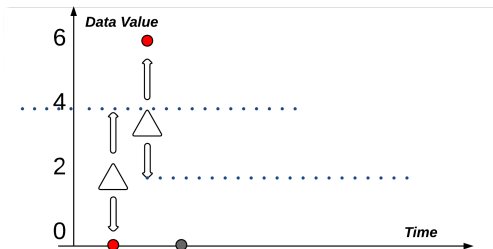


Tracking Component

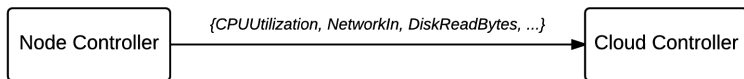


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
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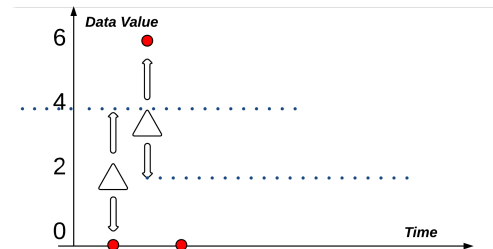


Tracking Component

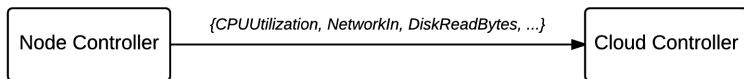


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:

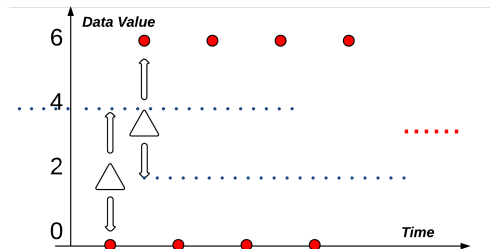


Tracking Component



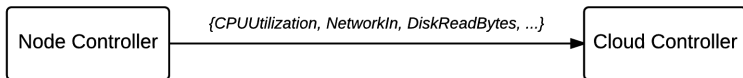
What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:



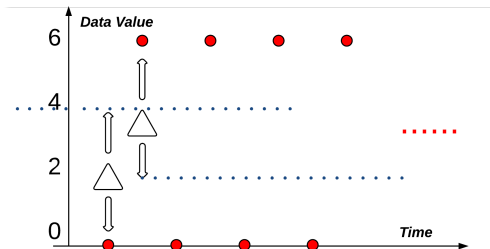
* Values sent: $\{0, 6, 0, 6, 0, 6, \dots\}$

Tracking Component



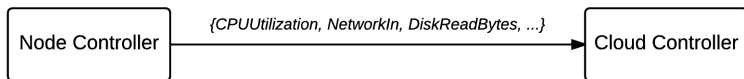
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- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
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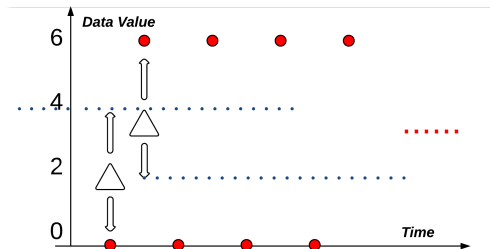
- * Values sent: $\{0, 6, 0, 6, 0, 6, \dots\}$
- * Optimal offline algorithm could only send one value: 3

Tracking Component



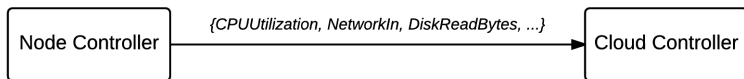
What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ A naive way:



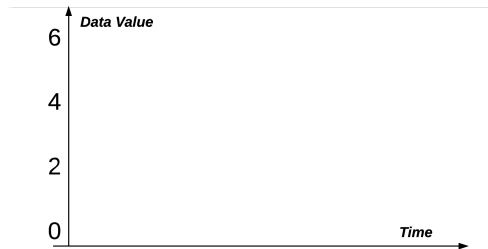
- * Values sent: $\{0, 6, 0, 6, 0, 6, \dots\}$
- * Optimal offline algorithm could only send one value: 3
- * Competitive ratio: Unbounded

Tracking Component

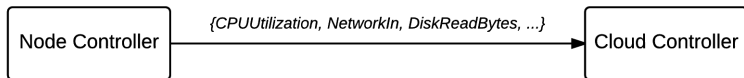


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ The optimal one dimension online tracking algorithm:

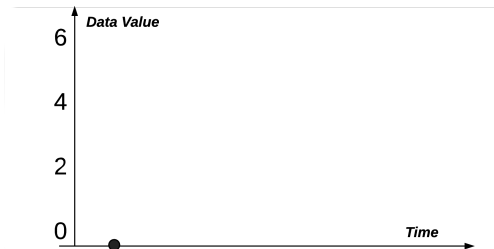


Tracking Component

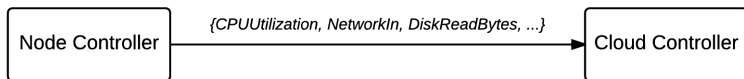


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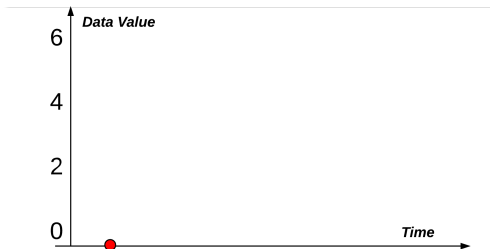


Tracking Component

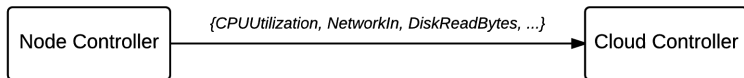


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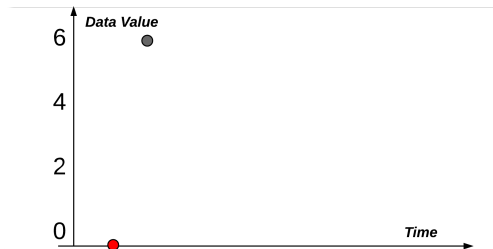


Tracking Component

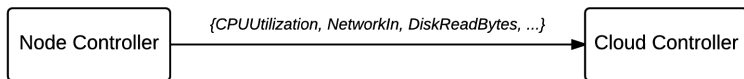


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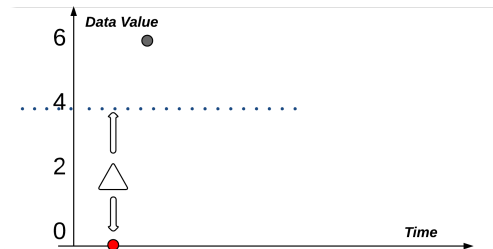


Tracking Component

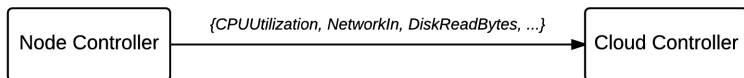


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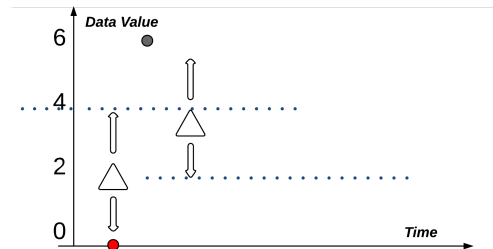


Tracking Component

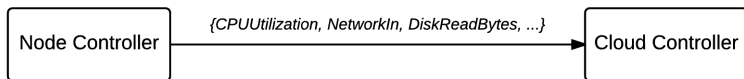


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- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
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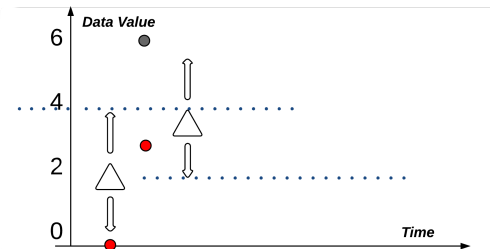


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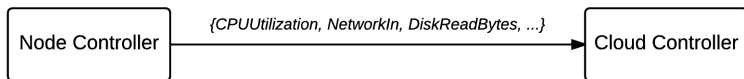


What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ The optimal one dimension online tracking algorithm:

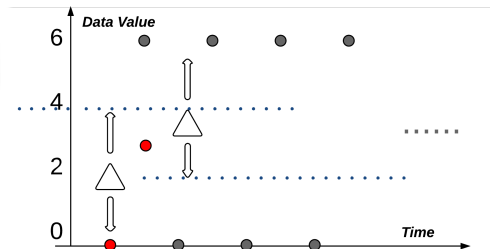


Tracking Component

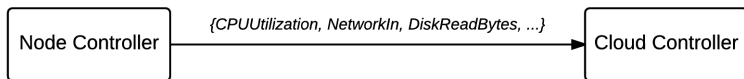


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- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
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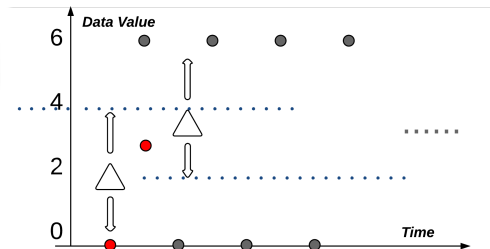


Tracking Component



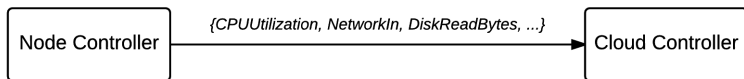
What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ The optimal one dimension online tracking algorithm:



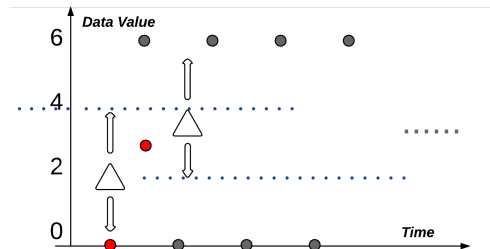
* Values sent: $\{0, 3\}$

Tracking Component



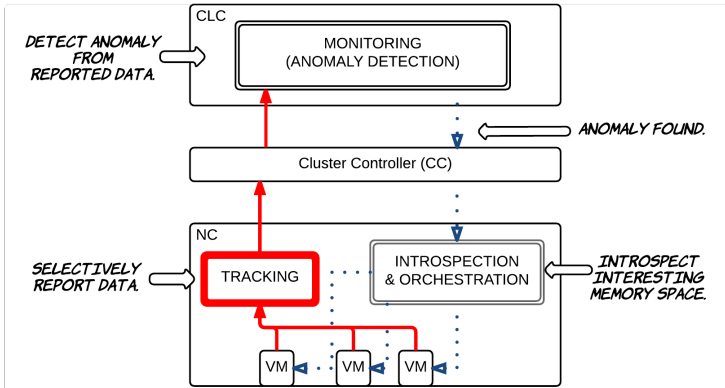
What if a small error Δ is allowed?

- ▶ Sequence: $\{0, 6, 0, 6, 0, 6, \dots\}$; $\Delta = 4$
- ▶ The optimal one dimension online tracking algorithm:

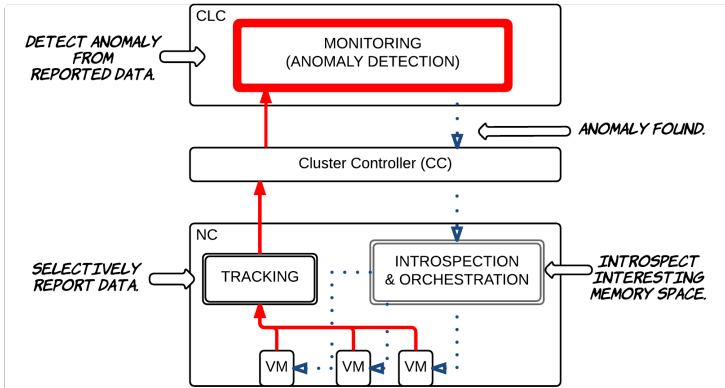


- * Values sent: $\{0, 3\}$
- * Competitive ratio: $\log \Delta$

Tracking Component



Monitoring Component



Monitoring Component

Monitoring Component

Data matrix reported from each node:

$$\underbrace{\left(\begin{array}{ccccc}
 V_{00} & V_{01} & V_{02} & \cdots & V_{0d} \\
 \vdots & & & \ddots & \\
 V_{(n-2)0} & V_{(n-2)1} & V_{(n-2)2} & \cdots & V_{(n-2)d} \\
 V_{(n-1)0} & V_{(n-1)1} & V_{(n-1)2} & \cdots & V_{(n-1)d} \\
 V_{(now)0} & V_{(now)1} & V_{(now)2} & \cdots & V_{(now)d}
 \end{array} \right)}_{d \text{ metrics}} \left. \vphantom{\begin{array}{c} \\ \\ \\ \\ \\ \end{array}} \right\} n \text{ time instances}$$

Monitoring Component

Data matrix reported from each node:

$$\underbrace{\left(\begin{array}{ccccc} V_{00} & V_{01} & V_{02} & \cdots & V_{0d} \\ \vdots & & & \ddots & \\ V_{(n-2)0} & V_{(n-2)1} & V_{(n-2)2} & \cdots & V_{(n-2)d} \\ V_{(n-1)0} & V_{(n-1)1} & V_{(n-1)2} & \cdots & V_{(n-1)d} \\ V_{(now)0} & V_{(now)1} & V_{(now)2} & \cdots & V_{(now)d} \end{array} \right)}_{d \text{ metrics}} \left. \vphantom{\begin{array}{c} V_{00} \\ \vdots \\ V_{(n-2)0} \\ V_{(n-1)0} \\ V_{(now)0} \end{array}} \right\} n \text{ time instances}$$

- ▶ Anomaly detection using this matrix;

Monitoring Component

Data matrix reported from each node:

$$\underbrace{\left(\begin{array}{ccccc} V_{00} & V_{01} & V_{02} & \cdots & V_{0d} \\ \vdots & & & \ddots & \\ V_{(n-2)0} & V_{(n-2)1} & V_{(n-2)2} & \cdots & V_{(n-2)d} \\ V_{(n-1)0} & V_{(n-1)1} & V_{(n-1)2} & \cdots & V_{(n-1)d} \\ V_{(now)0} & V_{(now)1} & V_{(now)2} & \cdots & V_{(now)d} \end{array} \right)}_{d \text{ metrics}} \left. \vphantom{\begin{array}{c} V_{00} \\ \vdots \\ V_{(n-2)0} \\ V_{(n-1)0} \\ V_{(now)0} \end{array}} \right\} n \text{ time instances}$$

- ▶ Anomaly detection using this matrix;
- ▶ Use Principal Component Analysis (PCA);

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- ▶ Anomaly detection using this matrix;
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- ▶ Sliding window;

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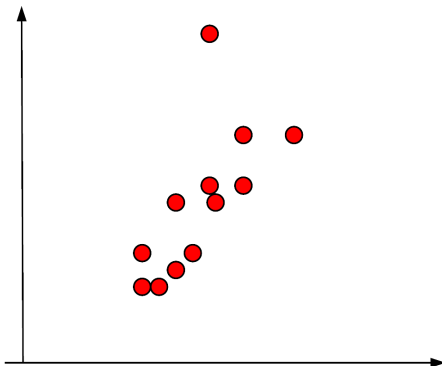
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- ▶ Anomaly detection using this matrix;
- ▶ Use Principal Component Analysis (PCA);
- ▶ Sliding window;
- ▶ Metrics identification after anomalies are detected.

Monitoring Component - Anomaly Detection

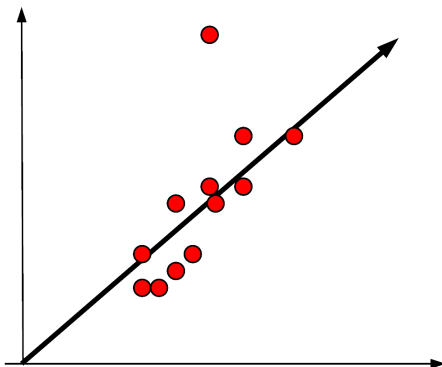
Monitoring Component - Anomaly Detection

PCA:



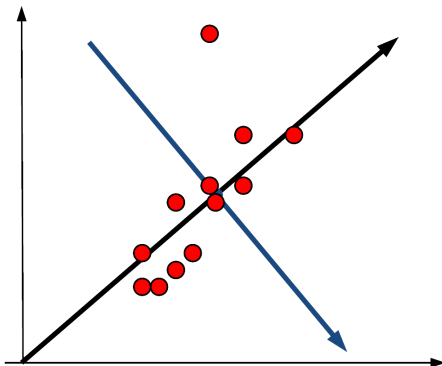
Monitoring Component - Anomaly Detection

PCA:



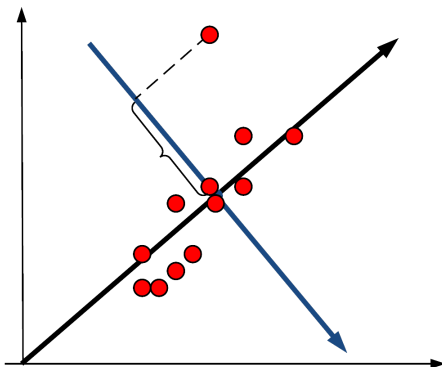
Monitoring Component - Anomaly Detection

PCA:



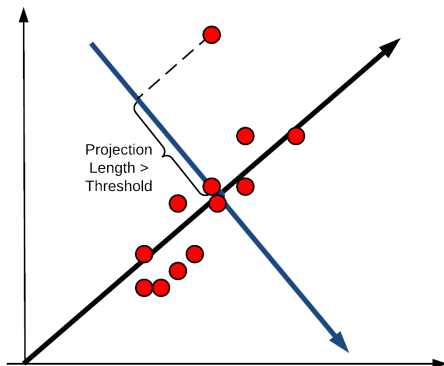
Monitoring Component - Anomaly Detection

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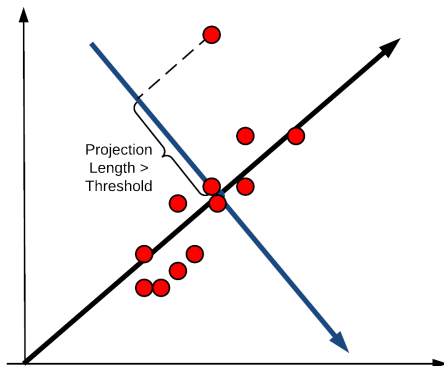
Monitoring Component - Anomaly Detection

PCA:



Monitoring Component - Anomaly Detection

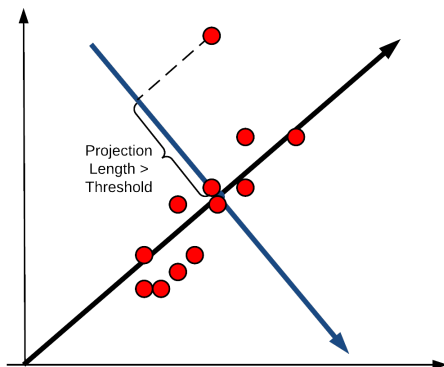
PCA:



- + Threshold Q_α is computed according to a given false alarm rate α .

Monitoring Component - Anomaly Detection

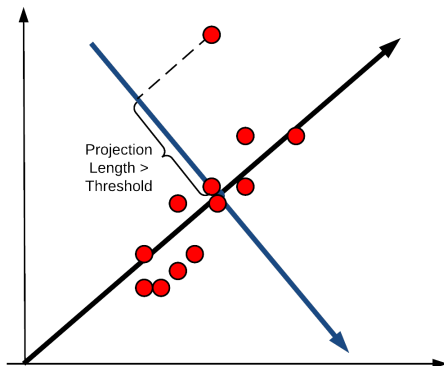
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Monitoring Component - Anomaly Detection

PCA:



- + Threshold Q_α is computed according to a given false alarm rate α .
- + Tracking component introduces error Δ to data matrix.
- + Given μ , dynamically adjust Δ according to PCA results, to ensure false alarm rate $\in (\alpha - \mu, \alpha + \mu)$

Monitoring Component - Metrics Identification

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Goal: Pinpoint the abnormal dimensions of suspicious data points to assist Orchestration component.

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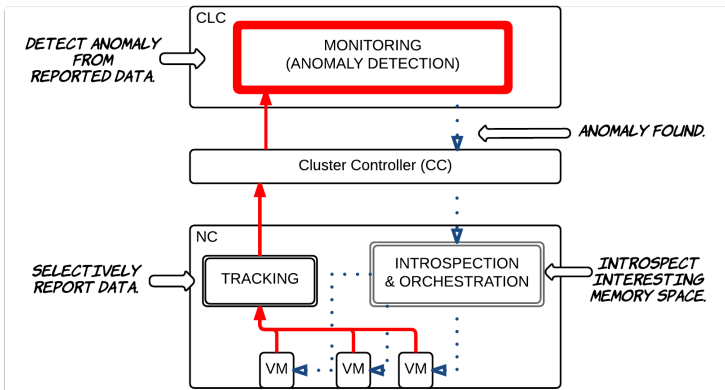
Monitoring Component - Metrics Identification

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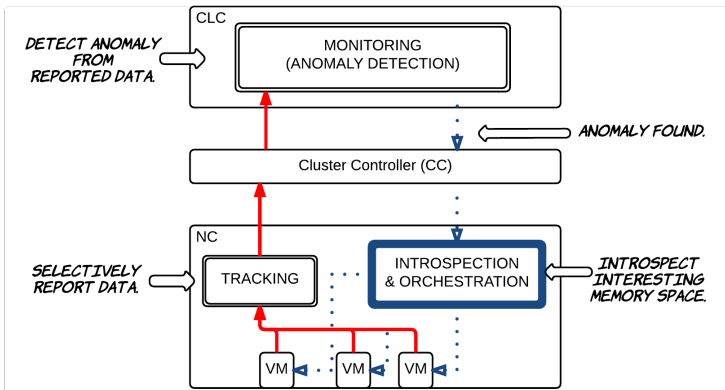
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 V_{(now)0} & \mathbf{V}_{(now)1} & \mathbf{V}_{(now)2} & \cdots & V_{(now)d}
 \end{pmatrix}$$

Main idea: Compare each dimension of the abnormal data points and normal ones.

Monitoring Component



Orchestration Component



Orchestration Component

Orchestration Component

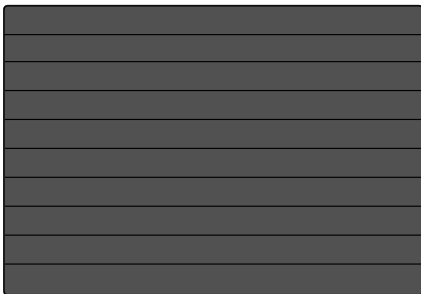
Virtual Machine Introspection (VMI)

- ▶ Introspect VM memory using existing VMI tools;

Orchestration Component

Virtual Machine Introspection (VMI)

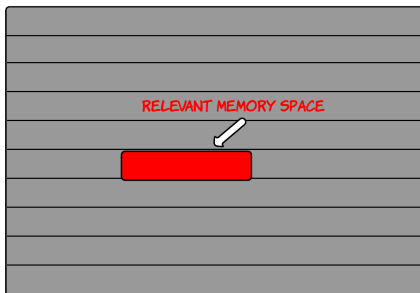
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Orchestration Component

Virtual Machine Introspection (VMI)

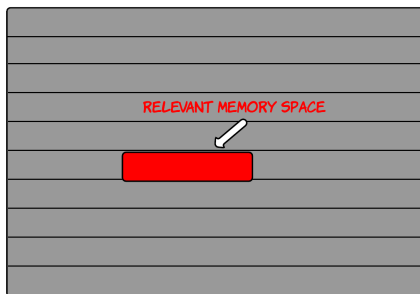
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Orchestration Component

Virtual Machine Introspection (VMI)

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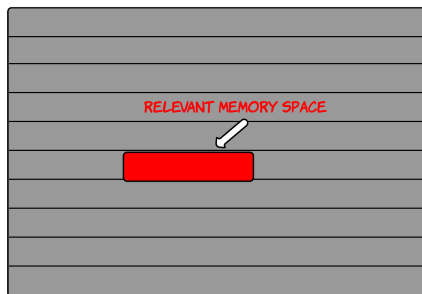


- ▶ Raise alarm;

Orchestration Component

Virtual Machine Introspection (VMI)

- ▶ Introspect VM memory using existing VMI tools;



- ▶ Raise alarm;
- ▶ Optionally, kill process.

Evaluation

- + Implemented on the Eucalyptus Cloud platform;

Evaluation

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- + Modified Node Controller and Cloud Controller source code.

Evaluation

Recall the two questions:

Evaluation

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1. Monitor more efficiently?

Evaluation

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1. Monitor more efficiently?
2. Utilize the statistics for security purpose?

Evaluation

Recall the two questions:

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 - ▶ Tracking Component
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Recall the two questions:

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 - ▶ Monitoring and Orchestration Component

Evaluation

Recall the two questions:

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Metrics monitored for each VM:

- The default 7 metrics monitored by Eucalyptus CloudWatch.

Evaluation - Tracking

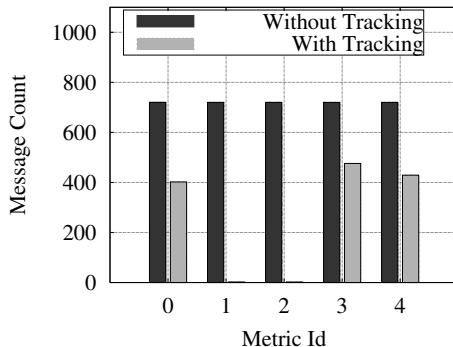
A comparison on number of values sent by NC for each metric.

- ▶ VM workload: TPC-C benchmark on MySQL database;
- ▶ Δ : The average for each metric when VM is **idle**.

Evaluation - Tracking

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Evaluation - Monitoring

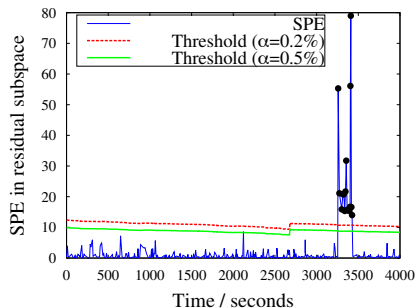
Experiment setting:

- ▶ 3 VMs being monitored: VM 1 idle, VM 2 and 3 run Apache web server;
- ▶ VM 2 and 3 are compromised as DDoS bots later.

Evaluation - Monitoring

Experiment setting:

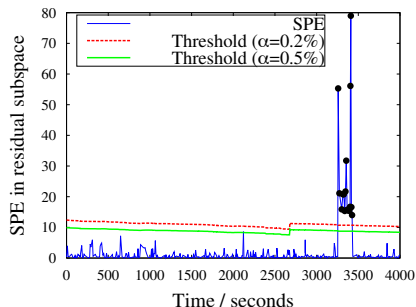
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Evaluation - Monitoring

Experiment setting:

- ▶ 3 VMs being monitored: VM 1 idle, VM 2 and 3 run Apache web server;
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Dim (j)	vm1-d1	vm1-d2	vm1-d3	vm1-d4	vm1-d5	vm1-d6	vm1-d7	vm2-d1	vm2-d2	vm2-d3	vm2-d4
rd_j	23.70	-0.98	-0.98	-0.55	-0.57	4.27	3.76	9.14	64.18	65.05	3.50
$stddev_j$	0.78	0.42	0.58	0.00	0.67	0.00	0.71	3.17	8.01	8.30	0.00
$meandiff_j$								0.16	-0.26	-0.28	
Dim (j)	vm2-d5	vm2-d6	vm2-d7	vm3-d1	vm3-d2	vm3-d3	vm3-d4	vm3-d5	vm3-d6	vm3-d7	
rd_j	-0.51	-0.82	4.23	9.04	60.56	61.16	1.45	-0.56	1.89	-0.51	
$stddev_j$	0.31	0.00	0.35	7.23	6.06	6.98	0.17	3.39	0.12	3.65	
$meandiff_j$				0.39	-0.23	-0.31					

Metrics Identification Result

Evaluation - Orchestration

- ▶ Received a VMI request with information:
 - ▶ A possible network problem;
 - ▶ Similar patterns for VM 2 and 3.

Evaluation - Orchestration

- ▶ Received a VMI request with information:
 - ▶ A possible network problem;
 - ▶ Similar patterns for VM 2 and 3.
- ▶ Node Controller call existing VMI tools to introspect:
 - ▶ VM 2: Volatility found suspicious DDoS process;
 - ▶ VM 3: Same with VM 2?
 - ▶ Raise alarm to user;
 - ▶ Kill the processes automatically using StackDB if confirmed.

Discussion - Overhead

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Overhead introduced:

- ▶ On NC: $O(1)$ to apply tracking algorithm and call VMI tools;
- ▶ On CLC: Depending on the PCA algorithm used, polynomial to sliding window size and number of dimensions monitored.

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- ▶ On NC: $O(1)$ to apply tracking algorithm and call VMI tools;
- ▶ On CLC: Depending on the PCA algorithm used, polynomial to sliding window size and number of dimensions monitored.

Overhead saved:

- ▶ Significant amount of network traffic sending from NC to CC to CLC;
- ▶ Significant amount of memory space to be introspected by VMI.

Discussion - Possible Extension

Discussion - Possible Extension

- ▶ Monitor more metrics;
- ▶ Extend VMI tools to find more complicated attacks.

Thank you.

Thank you.

Questions?