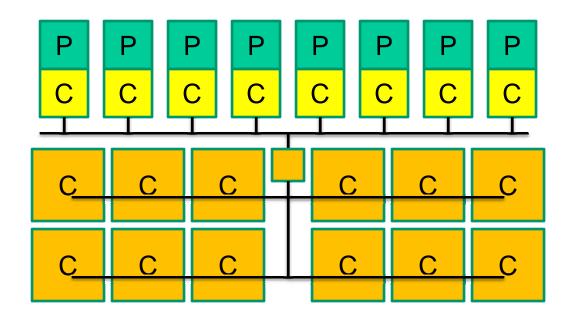
Lecture 2: Intro and Snooping Protocols

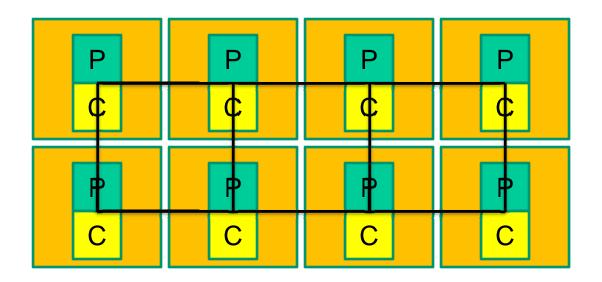
 Topics: multi-core cache organizations, programming models, cache coherence (snooping-based)



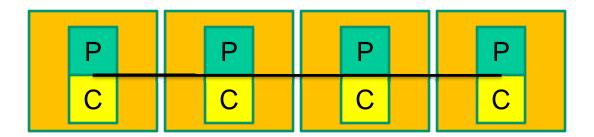
Private L1 caches

Shared L2 cache

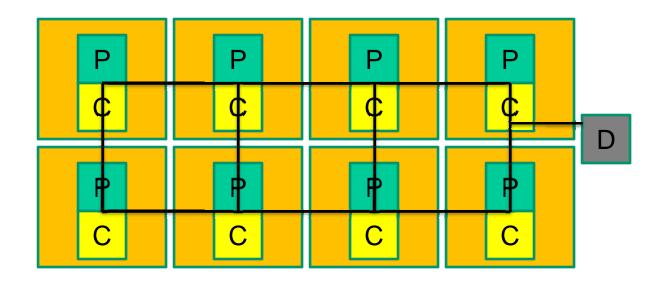
Bus between L1s and single L2 cache controller Snooping-based coherence between L1s



Private L1 caches
Shared L2 cache, but physically distributed
Scalable network
Directory-based coherence between L1s



Private L1 caches
Shared L2 cache, but physically distributed
Bus connecting the four L1s and four L2 banks
Snooping-based coherence between L1s



Private L1 caches

Private L2 caches

Scalable network

Directory-based coherence between L2s (through a separate directory)

Shared-Memory Vs. Message Passing

- Shared-memory
 - single copy of (shared) data in memory
 - threads communicate by reading/writing to a shared location
- Message-passing
 - each thread has a copy of data in its own private memory that other threads cannot access
 - threads communicate by passing values with SEND/ RECEIVE message pairs

Ocean Kernel

```
Procedure Solve(A)
begin
 diff = done = 0;
 while (!done) do
    diff = 0;
    for i \leftarrow 1 to n do
      for j \leftarrow 1 to n do
        temp = A[i,j];
        A[i,j] \leftarrow 0.2 * (A[i,j] + neighbors);
        diff += abs(A[i,j] - temp);
      end for
    end for
    if (diff < TOL) then done = 1;
 end while
end procedure
```

Shared Address Space Model

```
int n, nprocs;
float **A, diff;
LOCKDEC(diff_lock);
BARDEC(bar1);
main()
begin
  read(n); read(nprocs);
 A \leftarrow G_MALLOC();
  initialize (A);
  CREATE (nprocs, Solve, A);
  WAIT_FOR_END (nprocs);
end main
```

```
procedure Solve(A)
  int i, j, pid, done=0;
  float temp, mydiff=0;
  int mymin = 1 + (pid * n/procs);
  int mymax = mymin + n/nprocs -1;
  while (!done) do
    mydiff = diff = 0;
    BARRIER(bar1,nprocs);
    for i ← mymin to mymax
      for i \leftarrow 1 to n do
      endfor
    endfor
    LOCK(diff_lock);
    diff += mydiff;
    UNLOCK(diff_lock);
    BARRIER (bar1, nprocs);
    if (diff < TOL) then done = 1;
    BARRIER (bar1, nprocs);
  endwhile
```

Message Passing Model

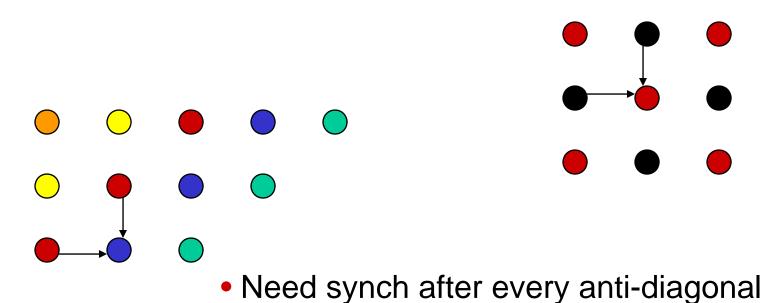
```
main()
                                                   for i \leftarrow 1 to nn do
 read(n); read(nprocs);
                                                     for j \leftarrow 1 to n do
  CREATE (nprocs-1, Solve);
  Solve();
                                                     endfor
  WAIT FOR END (nprocs-1);
                                                   endfor
                                                   if (pid != 0)
procedure Solve()
                                                    SEND(mydiff, 1, 0, DIFF);
  int i, j, pid, nn = n/nprocs, done=0;
                                                    RECEIVE(done, 1, 0, DONE);
 float temp, tempdiff, mydiff = 0;
                                                   else
  myA \leftarrow malloc(...)
                                                    for i \leftarrow 1 to nprocs-1 do
  initialize(myA);
                                                      RECEIVE(tempdiff, 1, *, DIFF);
  while (!done) do
                                                      mydiff += tempdiff;
    mydiff = 0;
                                                    endfor
    if (pid != 0)
                                                    if (mydiff < TOL) done = 1;
      SEND(&myA[1,0], n, pid-1, ROW);
                                                    for i ← 1 to nprocs-1 do
    if (pid != nprocs-1)
                                                      SEND(done, 1, I, DONE);
      SEND(&myA[nn,0], n, pid+1, ROW);
                                                    endfor
    if (pid != 0)
                                                   endif
      RECEIVE(&myA[0,0], n, pid-1, ROW);
                                                 endwhile
    if (pid != nprocs-1)
      RECEIVE(\&myA[nn+1,0], n, pid+1, ROW);
                                                                                  9
```

Models for SEND and RECEIVE

- Synchronous: SEND returns control back to the program only when the RECEIVE has completed
- Blocking Asynchronous: SEND returns control back to the program after the OS has copied the message into its space
 the program can now modify the sent data structure
- Nonblocking Asynchronous: SEND and RECEIVE return control immediately – the message will get copied at some point, so the process must overlap some other computation with the communication – other primitives are used to probe if the communication has finished or not

Deterministic Execution

- Shared-memory vs. message passing
- Function of the model for SEND-RECEIVE
- Function of the algorithm: diagonal, red-black ordering



Potential load imbalance

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Cache Coherence

A multiprocessor system is cache coherent if

- a value written by a processor is eventually visible to reads by other processors – write propagation
- two writes to the same location by two processors are seen in the same order by all processors – write serialization

Cache Coherence Protocols

- Directory-based: A single location (directory) keeps track of the sharing status of a block of memory
- Snooping: Every cache block is accompanied by the sharing status of that block – all cache controllers monitor the shared bus so they can update the sharing status of the block, if necessary
- Write-invalidate: a processor gains exclusive access of a block before writing by invalidating all other copies
- Write-update: when a processor writes, it updates other shared copies of that block

Protocol-I MSI

- 3-state write-back invalidation bus-based snooping protocol
- Each block can be in one of three states invalid, shared, modified (exclusive)
- A processor must acquire the block in exclusive state in order to write to it – this is done by placing an exclusive read request on the bus – every other cached copy is invalidated
- When some other processor tries to read an exclusive block, the block is demoted to shared

Design Issues, Optimizations

- When does memory get updated?
 - demotion from modified to shared?
 - move from modified in one cache to modified in another?
- Who responds with data? memory or a cache that has the block in exclusive state – does it help if sharers respond?
- We can assume that bus, memory, and cache state transactions are atomic – if not, we will need more states
- A transition from shared to modified only requires an upgrade request and no transfer of data
- Is the protocol simpler for a write-through cache?

4-State Protocol

- Multiprocessors execute many single-threaded programs
- A read followed by a write will generate bus transactions to acquire the block in exclusive state even though there are no sharers
- Note that we can optimize protocols by adding more states – increases design/verification complexity

MESI Protocol

- The new state is exclusive-clean the cache can service read requests and no other cache has the same block
- When the processor attempts a write, the block is upgraded to exclusive-modified without generating a bus transaction
- When a processor makes a read request, it must detect if it has the only cached copy – the interconnect must include an additional signal that is asserted by each cache if it has a valid copy of the block

Design Issues

- When caches evict blocks, they do not inform other caches – it is possible to have a block in shared state even though it is an exclusive-clean copy
- Cache-to-cache sharing: SRAM vs. DRAM latencies, contention in remote caches, protocol complexities (memory has to wait, which cache responds), can be especially useful in distributed memory systems
- The protocol can be improved by adding a fifth state (owner – MOESI) – the owner services reads (instead of memory)

Update Protocol (Dragon)

- 4-state write-back update protocol, first used in the Dragon multiprocessor (1984)
- Write-back update is not the same as write-through on a write, only caches are updated, not memory
- Goal: writes may usually not be on the critical path, but subsequent reads may be

4 States

- No invalid state
- Modified and Exclusive-clean as before: used when there is a sole cached copy
- Shared-clean: potentially multiple caches have this block and main memory may or may not be up-to-date
- Shared-modified: potentially multiple caches have this block, main memory is not up-to-date, and this cache must update memory – only one block can be in Sm state
- In reality, one state would have sufficed more states to reduce traffic

Design Issues

- If the update is also sent to main memory, the Sm state can be eliminated
- If all caches are informed when a block is evicted, the block can be moved from shared to M or E – this can help save future bus transactions
- Having an extra wire to determine exclusivity seems like a worthy trade-off in update systems

Examples

Total transfers:

```
P1 P2

MSI MESI Dragon MSI MESI Dragon

P1: Rd X

P1: Wr X

P2: Rd X

P1: Wr X

P1: Wr X

P1: Wr X

P2: Rd X

P2: Rd X

P2: Rd X

P2: Rd X
```

Title

Bullet