
L14: Parallel: Selection

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14.1 Selection

The selection problem is to find a k -th smallest element of A , and can be stated as follows:
Given an array A of n elements and an integer k , such that $1 \leq k \leq n$, find $a \in A$, such that
 $|a' \in A : a' < a| \leq k-1$, and
 $|a' \in A : a' > a| \geq n-k$

We describe here a technique known as Accelerating Cascades, to solve the selection problem. The Accelerating Cascades technique, in general, provides a way for taking several parallel algorithms for a given problem and deriving out of them a parallel algorithm, which is more efficient than any of them separately.

14.1.1 Model of Computation

The model of computation used here to solve the selection problem, is a PRAM model with concurrent reads and concurrent writes. That is, the model consists of a number of CPUs sharing a memory unit, and all CPUs can concurrently read and write from that memory unit.

The two quantities for this algorithm that we will measure are:

PTIME: This is the maximum time that any one CPU could take for computation.

Work: This is defined as the sum of the number of operations that CPUs perform.

14.1.2 Accelerating Cascades

For devising the fast $O(n)$ -work algorithm for the selection problem, we will use two algorithms to be run one after the other:

(1) Algorithm 1 works in $O(\log n)$ iterations. Each iteration takes an instance of the selection problem of size m and reduces it in $O(\log m)$ time and $O(m)$ work to another instance of the selection problem whose size is bounded by a fraction of m (specifically, $3m/4$). The total running time of this algorithm is $O(\log^2 n)$ and its total work is $O(n)$.

(2) Algorithm 2 is a sorting algorithm that runs in $O(\log n)$ time and $O(n \log n)$ work.

The advantage of Algorithm 1 is that it needs only $O(n)$ work, while the advantage of Algorithm 2 is that it requires less time. The benefit of accelerating cascades technique is that it combines these two algorithms into a single algorithm that is both fast and needs only $O(n)$ work. The main idea is to start with Algorithm 1, but, instead of running it to completion, switch to Algorithm 2.

Algorithm 1 Algorithm 1 works in reducing iterations. Input to each iteration is an array B of size m and an integer t , $1 \leq t \leq m$. Given a selection problem to be solved for an array A of size n and an integer k , we begin by passing A as the array ($B = A$), size as n ($m = n$) and integer as k ($t = k$). Algorithm 1 is applied for $O(\log \log n)$ rounds, which reduces the original instance of problem to a size $\leq n/\log n$. An iteration is described as follows:

Algorithm 14.1.1 Selection(B, m, t)

Partition $B \rightarrow B_1, B_2, B_3, \dots B_i, \dots B_{m/\log m}$
for $i = 1$ **to** $m/\log m$ **parado**
 $x_i = \text{seq} - \text{median}(B_i)$
 $x = \text{median}(x_1, x_2, x_3, \dots x_{m/\log m})$
 $B \rightarrow \{L, M, R\}$, where
 $L = \{a \in B : a < x\}$
 $M = \{a \in B : a = x\}$
 $R = \{a \in B : a > x\}$
if $|L| > t$
 Do the iteration as *Selection*(L, t)
else if $|L| + |M| < t$
 Do the iteration as *Selection*($R, t - |L| - |M|$)
else
 return x

Algorithm 2 Algorithm 2 is a parallel-sorting algorithm for which,
PTime is $O(\log m) = O(\log n)$, and
Work is $O(m \log m) = O(n)$
 $*m = n/\log n$

Complexity Analysis We first prove that $r = O(\log \log n)$ rounds are sufficient to bring the size of the problem below $n/\log n$. To get $(3/4)^r n \leq n/\log n$, we need $(4/3)^r \geq \log n$. The smallest value of r for which this holds is $\log_{4/3} \log n$, which is equivalent to $O(\log \log n)$. Therefore, the Algorithm 1 takes $O(\log n \log \log n)$ PTime. Amount of Work is $\sum_{i=0}^{r-1} (3/4)^i n = O(n)$. Algorithm 2 takes $O(\log n)$ PTime and $O(n)$ Work. So in total we take $O(\log n \log \log n)$ PTime and $O(n)$ Work.

14.2 Max

The input is going to be an unsorted set A . $|A| = n$. We should find the largest element. So the sequential time should be $O(n)$. Also, the cost of PRAM and work are $O(\log \log n)$ and $O(n)$ separately.

14.2.1 Algorithm 1

The PTime is $O(1)$, and work is $O(n^2)$. To find the max number, we need do a lot of comparisons among elements. There are n^2 possible comparisons in this operation. What we gonna do is compare all the $O(n^2)$ pairs in parallel. For example:

$$A \begin{array}{|c|c|c|c|} \hline & & a_i & \dots & a_j & \\ \hline \end{array}$$
$$B \begin{array}{|c|c|c|c|} \hline 1 & 1 & 1 & \dots & 1 & 1 \\ \hline \end{array}$$

Let's compare the a_i and a_j . If a_j smaller than a_i , a_j would be lost. Then change the 1 to 0 correspondingly in array B. Compare all elements like a_i and a_j and change the corresponding 1 to 0 in array B. After all these comparisons, only the elements which larger than the others should be 1 in array. Naturally these elements should be the max elements.

Since it is parallel operation, it is totally possible that after every comparison, they will modify array B concurrently. The hardware should allow concurrently write like this. It doesn't matter the order to write the 0 because they should all should be written. Of course it is more easy for hardware to implement this and the array B can be seen as bit array.

14.2.2 Algorithm 2

The next algorithm PTime is $O(\log \log n)$, and work is $O(n \log \log n)$. What we are going to do is subdivide A into \sqrt{n} equal sized sub-arrays. For example:

$$\begin{aligned} A1 &= \boxed{a_1} \boxed{a_2} \dots \boxed{a_{\sqrt{n}}} \boxed{} \\ A2 &= \boxed{a_{1+\sqrt{n}}} \boxed{} \dots \boxed{a_{2\sqrt{n}}} \boxed{} \\ &\dots \\ A_{\sqrt{n}} &= \boxed{a_{n-\sqrt{n}}} \boxed{} \dots \boxed{a_n} \boxed{} \end{aligned}$$

Algorithm 14.2.1 Algorithm 2

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for  $i = 1$  to  $\sqrt{n}$  do
   $x_h = \text{Algorithm2} - \text{Max}(A_h)$ 
 $X = x_1, \dots, x_{\sqrt{n}}$ 
return  $\text{Algorithm1} - \text{Max}(X)$ 
```

Algorithm 2 Analysis The big O notation of time is $T(n) = T(\sqrt{n}) + O(1) = O(\log \log n)$, and the work takes $W(n) = \sqrt{n} W(\sqrt{n}) + O(n) = O(n \log \log n)$. Note that for some t , $n = 2^{2^t}$, then $\sqrt{n} = \sqrt{2^{2^t}} = 2^{2^{t-1}}$ < – doubly geometrically decreasing.

Accelerating Cascades The steps of Accelerating Cascades are as followed:

- 1. Divide A into $n / \log \log n$ blocks $A_1, A_2, \dots, A_{n / \log \log n}$ each of size $\log \log n$.
- 2. Get the max element and return.

Algorithm 14.2.2 Accelerating Cascades

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for  $i = 1$  to  $\log \log n$  do
   $x_h = \text{Linear} - \text{Max}(A_i)$ 
 $X = x_1, \dots, x_{n / \log \log n}$ 
return  $x = \text{Algorithm2} - \text{Max}(X)$ 
```

Step 1 takes $O(\log \log n)$ time, and $O(n)$ work.

Step 2 takes $O(\log \log n)$ time, and $(n / \log \log n) * \log \log n = O(n)$ work.